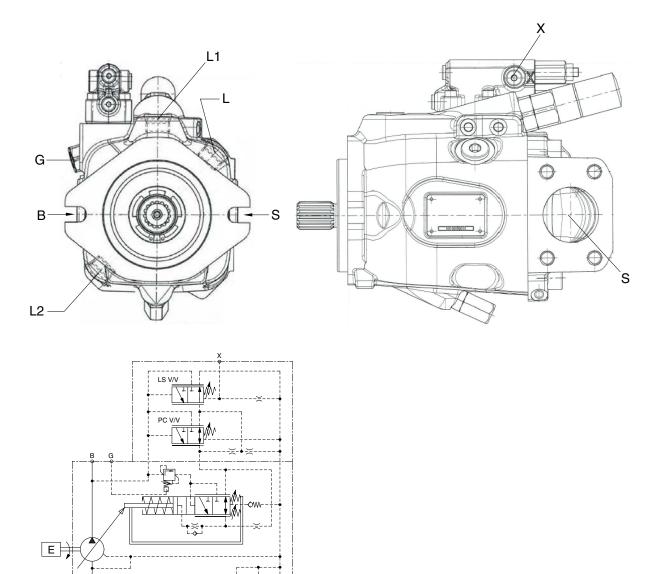
SECTION 2 STRUCTURE AND FUNCTION

Group	1 Pump Device ·····	2-1
Group	2 Main Control Valve	2-10
Group	3 Swing Device	2-43
Group	4 Travel Device	2-47
Group	5 RCV Lever ·····	2-62
Group	6 RCV Pedal	2-77

GROUP 1 HYDRAULIC PUMP

1. GENERAL

This main pump is variable displacement piston type with load sensing system.



Hydraulic circuit

---- L2 L1

55ACR2MP01

Description of the ports

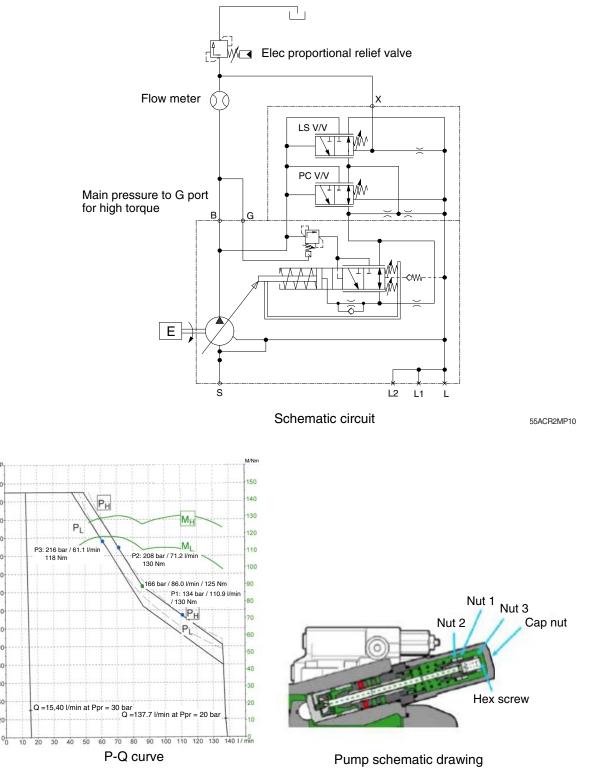
Port	Name	Bore	
S Suction port		SAE 2"	
B Discharge port		SAE 1"	
G High pressure port for dual torque function		M10x1	
X Pilot pressure port		PF7/16-20UNF	
L, L1, L2	Case drain port	PF7/8-14UNF	

2. START OF POWER CONTROL

Setting of starting point in P-Q curve shall be carried out as per following conditions and procedures.

1) CONDITIONS

- (1) Engine shall be running at 2000 rpm.
- (2) Oil temperature shall be adjusted at 40 $^{\circ}$ C.
- (3) Pressure gauges and a flow meter shall be installed.



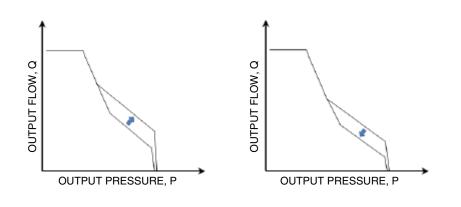
55ACR2MP11

2) PROCEDURES

- (1) Loosen nut 1 fixing nut 2.
- (2) Adjust outer spring by tightening or loosening nut 2.
- 1 Increase pressure up to 170 bar.
- 2 Turn Nut 2 clockwise to increase power until pumping flow reaches 123 ℓ /min (±4 ℓ /min).
- (3) Secure the setting of nut 2 by tightening nut 1.

3) CHANGE OF P-Q CURVE

- (1) If length of outer spring is decreased by tightening nut 2, the P-Q curve is moved to right in general like a graph left under as the spring tension is increased.
- (2) If length of outer spring is increased by loosening nut 2, the P-Q curve is moved to left in general like a graph right under as the spring tension is decreased.



85A2MP12

3. END OF POWER CONTROL

Setting of ending point in P-Q curve shall be carried out following procedures and conditions.

1) CONDITIONS

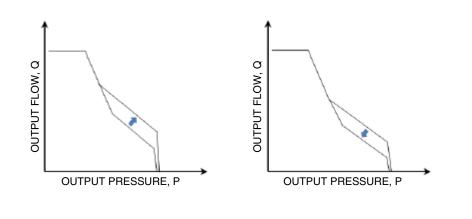
(1) The conditions shall be set same as above.

2) PROCEDURES

- (1) Loosen the nut 3.
- (2) Set end of control by turning Hexagonal screw.
- 1 Increase pressure to 220 bar.
- 2 Turn Screw clockwise to increase power until 92 $\,\ell\,$ /min (±4 $\ell\,$ /min) is reached.
- (3) Secure the setting of nut 3.
- (4) Tighten Cap nut.

3) CHANGE OF P-Q CURVE

- (1) If length of Inner spring is deceased by tightening hexagonal screw, lower part of P-Q curve is moved to right like a graph left under as the tension force of spring is increased.
- (2) If length of Inner spring is increased by loosening hexagonal screw, lower part of P-Q curve is moved to left like a graph left under as the tension force of spring is decreased.



85A2MP13

4. APPENDIXES

Required torque for bolt tightening

Part	Name	Required torque		
Fait		kgf∙m	lbf·ft	
Nut 1	14 mm	5.1	36.9	
Nut 2	14 mm	5.1	36.9	
Nut 3	10 mm	4.1	29.7	
Cap nut	32 mm	7.1	51.4	
Hexagon screw	10 mm	-	-	

5. DUAL TORQUE MODE

Pump power needs to be decreased in case that engine power is not enough to cover air condition operating at maximum pump operating. This function lets the pump power decrease by operating of dual torque valve.

(1) Normal operating condition (without air conditioner mode)

Solenoid valve (7) maintains the pushed position and allows oil to flow from passage (15) to passage (19). The pressure pushes dual torque valve (5) not to allow the pumping oil to flow toward control valve (6) inside. As a result, pressure in front of dual torque valve (5) does not effect on the angle of swash plate (25).

(2) Excessive operating condition (by air conditioner mode)

If air conditioner operates with maximum pump operating, the increased power will overload engine. Therefore, pump power needs to be decreased to share power consumption with air conditioner without overload to engine.

Connection between passage (15) and passage (19) is blocked by deactivation of solenoid valve (7). Dual torque valve which was pushed by the pressure in passage (19) also returns to initial position by spring force. This return allows the pumping oil to flow toward control valve (6) inside. The angel of swash plate (25) is decreased by the pressure in control valve. As a result, pump flow is decreased and power consumption by pump also is decreased.

6. UPSTROKE

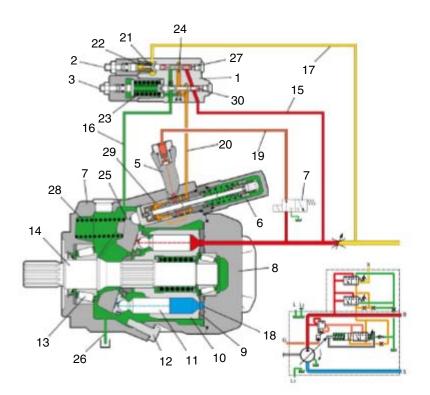
Upstroking of the pump occurs as a demand for flow from attachment.

The increased demand for flow causes a LS pressure in passage (17). The LS pressure in passage (17) combines with the force of spring (22) in cavity (21). The force of spring (22) causes pump pressure to be higher than pressure of passage (17).

If the combination of LS pressure and spring force is greater than the pump discharge pressure in passage (15), this difference pressure causes a spool (27) to move right. As the spool (27) moves right, the spool (27) blocks inflow of pumping oil to control piston (6) through passage (20). Swash plate (25) is controlled by pressure and flow as much as hydraulic system requests.

Pilot oil in passage (20) drains to passage (24). The oil then flows into housing through passage (16) into the housing and finally drains to tank. It also causes pumping flow to increase. As flow requirement is satisfied, pump output pressure increases. The pressure increases until the pressure in passage (24) moves flow compensator spool (27) up to be satisfied with system requirement for pressure and flow.

 \cdot Pump discharge pressure = force of spring (22) + LS pressure (17)



- 1 Regulator
- 2 Flow adjustment screw
- 3 Pressure adjustment screw
- 4 Pump housing
- 5 Dual torque valve
- 6 Control valve
- 7 Solenoid valve
- 8 Port plate
- 9 Distributor plate
- 10 Cylinder block
- 11 Piston
- 12 Minimum flow limitation valve

- 13 Bearing
- 14 Drive shaft
- 15 Passage (high pressure)16 Passage (leakage
- pressure)
- 17 Passage (pilot pressure)
- 18 Passage (suction pressure)
- 19 Passage (dual torque valve pilot pressure)
- 20 Passage (control piston pilot pressure)

- 21 Cavity
- 22 Spring
- 23 Spring
- 24 Passage
- 25 Swash plate
- 26 Casing drain
- 27 Flow compensator spool

85A2MP14

- 28 Spring
- 29 Cross drilled hole
- 30 Pressure compensator spool

7. DESTROKE

The decreased flow demand causes LS pressure in passage (17). LS pressure in passage (17) combines with force of spring (22) in cavity (21).

This combination of LS pressure and spring force is less than the pump pressure in passage (15). It causes flow compensator spool (27) to move left.

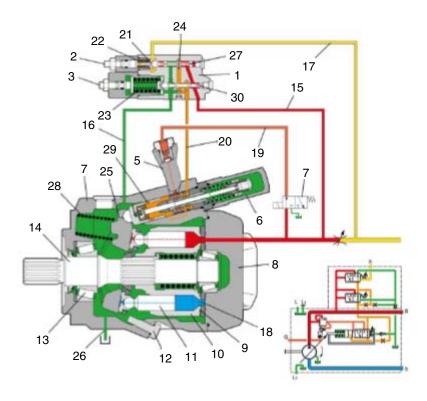
Pumping oil now flows through passage (15). The oil then flows past flow compensator spool (27), and then to control piston (6) through passage (20).

Combined force of pump pressure behind control piston (6) and counter spring (28) is bigger than force of springs inside control piston (6). Angle of swash plate (25) decreases.

This action results in decreasing of pump output and system pressure.

When the flow is decreased enough, flow compensator spool (27) moves right up to the balance position.

Swash plate (25) maintains the angle that is sufficient to provide the lower required pressure. If the operator does not operate RCV lever or pedal, the pump will return to low pressure stand-by.



85A2MP15

8. LOW PRESSURE STAND-BY

Low pressure standby constitutes the following condition: a running engine and inactive attachment. There is no flow demand or pressure demand on the pump. Therefore, there is no LS pressure in passage (17).

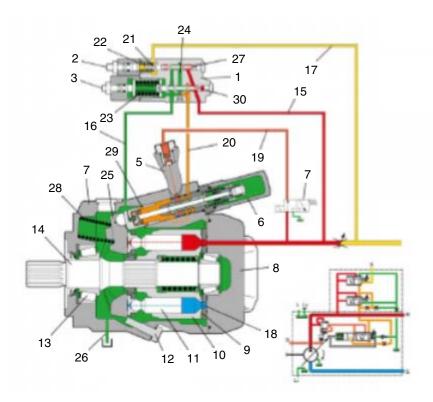
Before you start the engine, counter spring (28) holds swash plate (25) at the maximum angle. As the pump begins to operate, oil begins to flow and pressure increases in the system.

As the pressure increases, the pressure pushes flow compensator spool (27) against spring (22). It causes flow compensator spool (27) to move left. It opens passage (24) in order to allow pumping oil to flow to control piston (6) via passage (20).

The oil acts against control piston (6) in order to overcome the force of counter spring (28). The oil causes control piston (6) to move to the left. When control piston (6) moves to the left, the piston moves swash plate (25) toward the minimum angle. Control piston (6) continues to move to the left until cross-drilled hole (29) allows the oil to drain to pump housing. Cross-drilled hole (29) limits the maximum travel of control piston (6) toward the left.

The pump supplies a sufficient amount of flow that can compensate for the system leakage and the pump leakage. The leakage to the pump housing is flowed from the cross-drilled hole. The pump maintains low pressure stand-by. Low pressure stand-by should not exceed 15 bar.

* Low pressure standby will vary in the same pump as the system leakage or the pump leakage increases. The pump will slightly upstroke in order to compensate for the leakage increasing. Control piston (6) will cover much flow control than the flow through the cross-drilled hole.



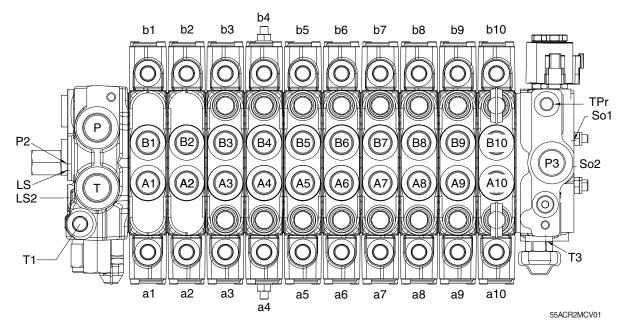
85A2MP16

9. CUT OFF FUNCTION

Once sudden pressure increasing in LS line occurs while attachments work, flow decreasing should be a necessary function to prevent a shock inside the pump. When high pressure in passage (15) flows to regulator (1), spools are likely to move by its force. However, shift of flow compensator spool (27) is restricted by LS pressure pushing spring (22) which is generated from attachments. Therefore, flow compensator spool (27) still blocks a connection from passage (27) to passage (24). The flow blocked by flow compensator spool (27) alternatively shifts pressure compensator spool (30) to right. Passage (15) connects to passage (20) by this shift. High pressure flows to control valve (6), then decreases an angle of swash plate (25). Pumping flow finally will decrease by shift of flow compensator spool (27) although flow compensator spool (27) does not shift.

GROUP 2 MAIN CONTROL VALVE

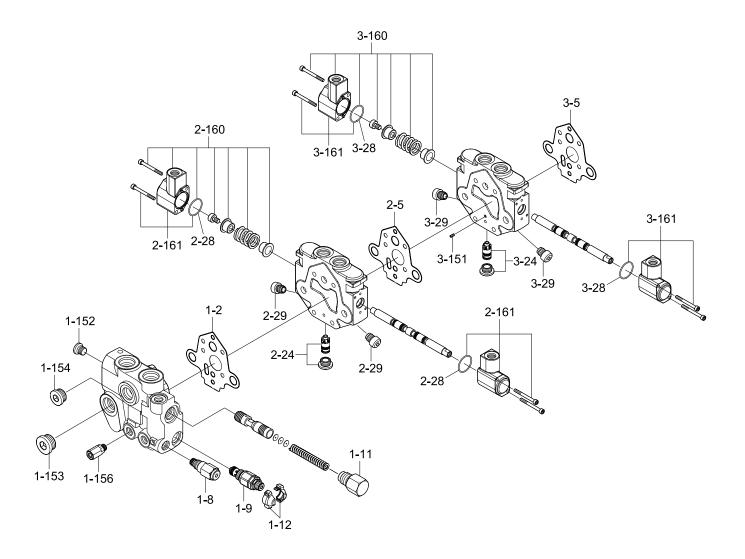
1. OUTLINE



Mark	Port name	
Р	Pump port	
P3	Pump port	
A4	Swing port (LH)	
B4	Swing port (RH)	
A7	Dozer down port	
B7	Dozer up port	
A8	Boom swing port (LH)	
B8	Boom swing port (RH)	
A10	Rotating port-CCW	
B10	Rotating port-CW	
A5	Arm out port	
B5	Arm in port	
A2	Travel port [LH/FW]	
B2	Travel port [LH/RR]	
A1	Travel port [RH/FW]	
B1	Travel port [RH/RR]	
A3	Boom up port	
B3	Boom down port	
A6	Bucket in port	
B6	Bucket out port	
A9	Auxiliary 1 port (opt)	
B9	Auxiliary 1 port (opt)	
Т	Tank return port	
T1, T3	Tank return port	
a4	Swing pilot port (LH)	

Mark	Port name	
b4	Swing pilot port (RH)	
a7	Dozer down pilot port	
b7	Dozer up pilot port	
a8	Boom swing pilot port (LH)	
b8	Boom swing pilot port (RH)	
a10	Rotating pilot port-CCW	
b10	Rotating pilot port-CW	
a5	Arm out pilot port	
b5	Arm in pilot port	
a2	Travel pilot port (LH/FW)	
b2	Travel pilot port (LH/RR)	
a1	Travel pilot port (RH/FW)	
b1	Travel pilot port (RH/RR)	
a3	Boom up pilot port	
b3	Boom down pilot port	
a6	Bucket in pilot port	
b6	Bucket out pilot port	
a9	Auxiliary 1 pilot port (opt)	
b9	Auxiliary 1 pilot port (opt)	
LS	S Load sensing port	
LS2	Load sensing port	
TPr	Drain port	
So1	Pilot out port	
So2	Travel speed port	

2. STRUCTURE (1/4)



1 Inlet block assy

- 1-2 Plate seal
- 1-8 Flow regulator
- 1-9 Relief valve
- 1-11 Plug
- 1-12 Locking cover
- 1-12 Locking cover
- 1-152 Sealing plug
- 1-153 Sealing plug

1-154 Sealing plug

1-156 Shuttle valve

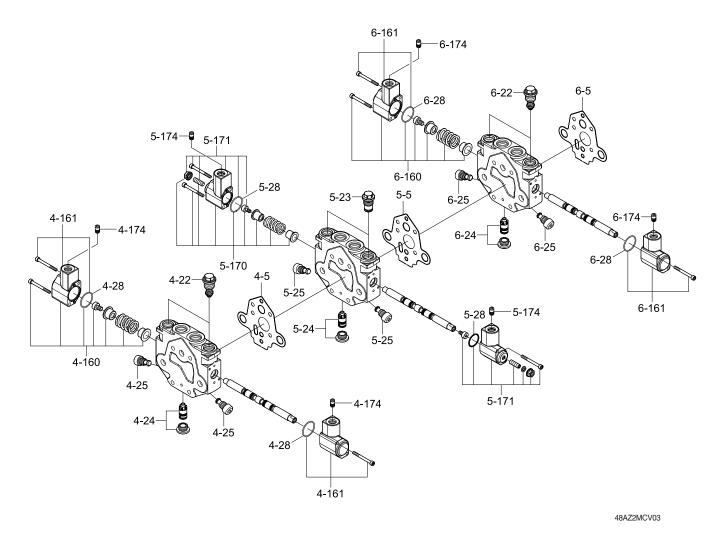
- 2 Travel block assy
- 2-5 Plate seal
- 2-24 Compensator kit
- 2-28 Seal kit
- 2-29 Orifice plug
- 2-160 W/spool cover kit
- 2-161 Cover kit

3 Travel block assy

55ACR2MCV02

- 3-5 Plate seal
- 3-24 Compensator kit
- 3-28 Seal kit
- 3-29 Orifice plug
- 3-151 Throttle screw
- 3-160 W/spool cover kit
- 3-161 Cover kit

STRUCTURE (2/4)

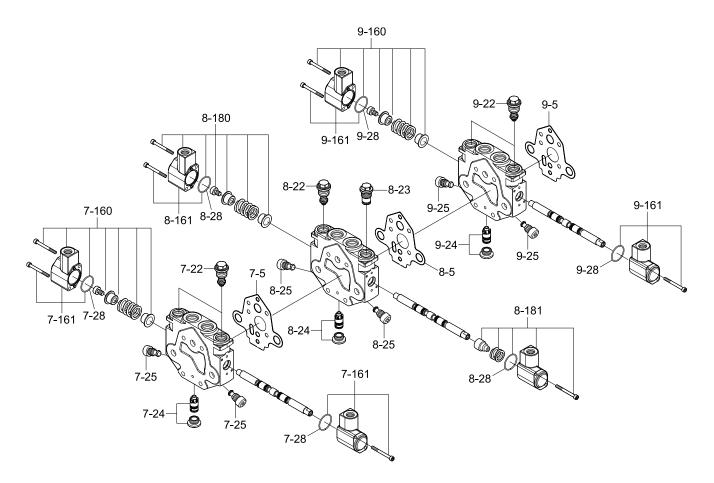


- 4 Boom block assy
- 4-5 Plate seal
- 4-22 Relief valve
- 4-24 Compensator kit
- 4-25 Check valve
- 4-28 Seal kit
- 4-160 W/spool cover kit
- 4-161 Cover kit
- 4-174 Snubber

- 5 Swing block assy
- 5-5 Plate seal
- 5-23 Plug
- 5-24 Compensator kit
- 5-25 Check valve
- 5-28 Seal kit
- 5-170 W/spool cover kit
- 5-171 Cover kit
- 5-174 Snubber

- 6 Arm block assy
- 6-5 Plate seal
- 6-22 Relief valve
- 6-24 Compensator kit
- 6-25 Check valve
- 6-28 Seal kit
- 6-160 W/spool cover kit
- 6-161 Cover kit
- 6-174 Snubber

STRUCTURE (3/4)



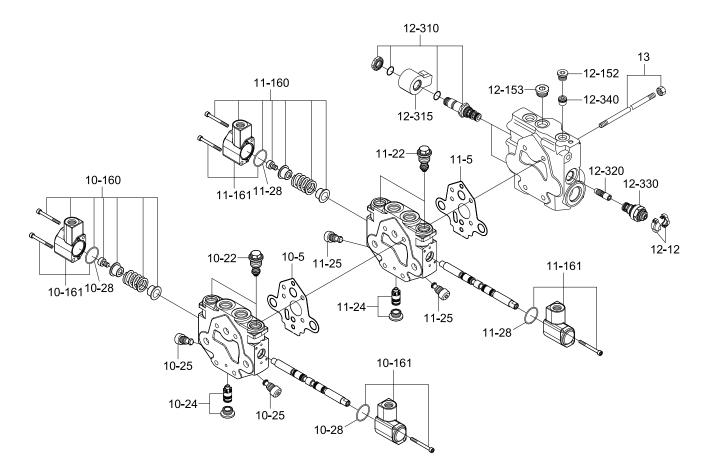
48AZ2MCV04

- 7 Bucket block assy
- 7-5 Plate seal
- 7-22 Relief valve
- 7-24 Compensator kit
- 7-25 Check valve
- 7-28 Seal kit
- 7-160 W/spool cover kit
- 7-161 Cover kit
 - 8 Dozer block assy

- 8-5 Plate seal
- 8-22 Anticavitation valve
- 8-23 Plug
- 8-24 Compensator kit
- 8-25 Check valve
- 8-28 Seal kit
- 8-161 Cover kit
- 8-180 W/spool cover kit
- 8-181 W/spool cover kit

- 9 Boom swing block assy
- 9-5 Plate seal
- 9-22 Relief valve
- 9-24 Compensator kit
- 9-25 Check valve
- 9-28 Seal kit
- 9-160 W/spool cover kit
- 9-161 Cover kit

STRUCTURE (4/4)



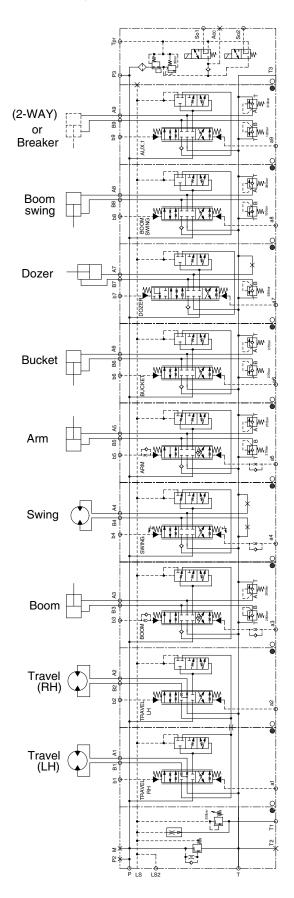
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- Aux 1 block assy
 Plate seal
 Plate seal
 Relief valve
 Compensator kit
 Check valve
- 10-28 Seal kit
- 10-160 W/spool cover kit
- 10-161 Cover kit
 - 11 Aux 2 block assy

11-5 Plate seal
11-22 Relief valve
11-24 Compensator kit
11-25 Check valve
11-28 Seal kit
11-160 W/spool cover kit
11-161 Cover kit
12 Outlet block assy
12-12 Locking cover

- 12-152 Sealing plug
- 12-153 Sealing plug
 - 12-310 Valve kit
 - 12-315 Solenoid
 - 12-320 Shuttle
 - 12-330 Pressure relief valve
 - 12-340 Filter
 - 13 Tie rod

3. HYDRAULIC CIRCUIT (boom swing, 2-way)

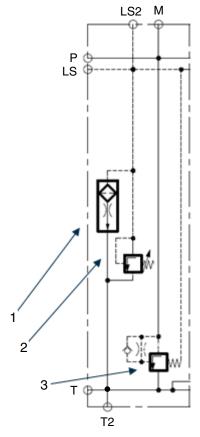


55ACR2MCV06

4. FUNCTION

1) INLET ELEMENT DESCRIPTION

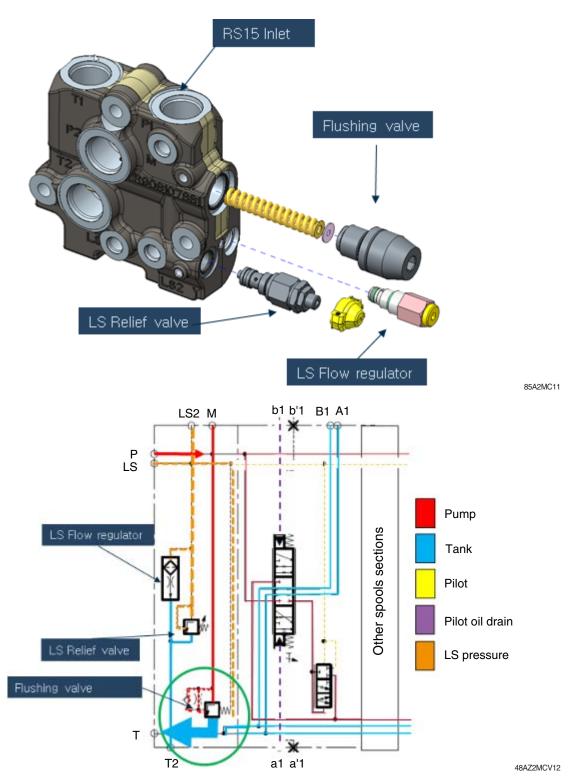
- The inlet plate has the line connections P, T, LS, T2 and M.
- The inlet element moreover comprises all components necessary for the system function: One flow control valve (1) for the controlled unloading of the LS line and one LS pressure relief valve (2) to limit the maximum system pressure.
- Protection of the system by means of LS pressure relief valve (2) combined with flushing valve (3).



48AZ2MCV10

(1) Inlet description - all spools at neutral position

First section-travel-represented at neutral



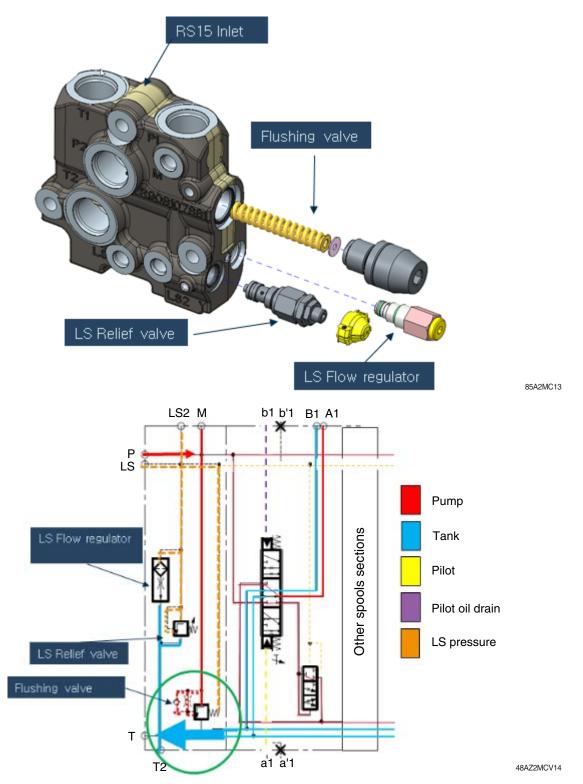
The Inlet element allows the exchange of the in the flow from the pump and the out flow to the tank.

When all sections are in neutral position, the pump is in stand-by and flow is reduced to the minimum pump flow (14 ℓ /min).

All the minimum pump flow pass through the flushing valve which is open, it means connected to the tank.

(2) Inlet description - spool actuated

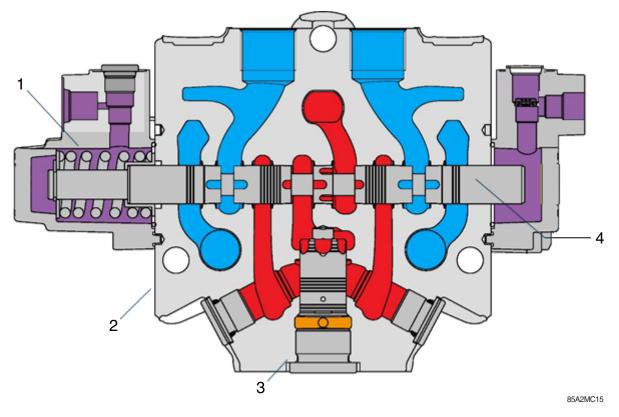
First section-travel-PABT spool position represented.

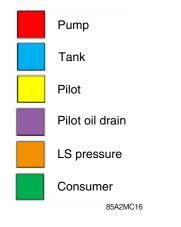


As soon as one or more spool moves, the flow stop to pass trough the flushing valve, which is closed, not anymore connected to the tank. The flow pass trough the spool to reach the movement, and then go to the tank by the T line after the spool.

2) TRAVEL SECTION DESCRIPTION - SECTION 1 AND 2

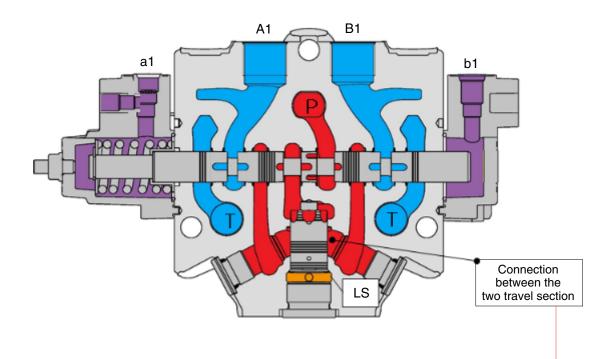
(1) Component description



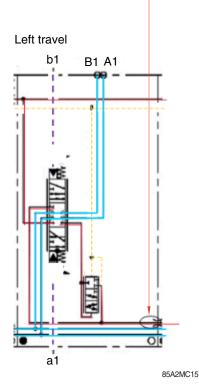


- 1 Spring pack
- 2 Housing
- 3 Pressure compensator
- 4 Spool

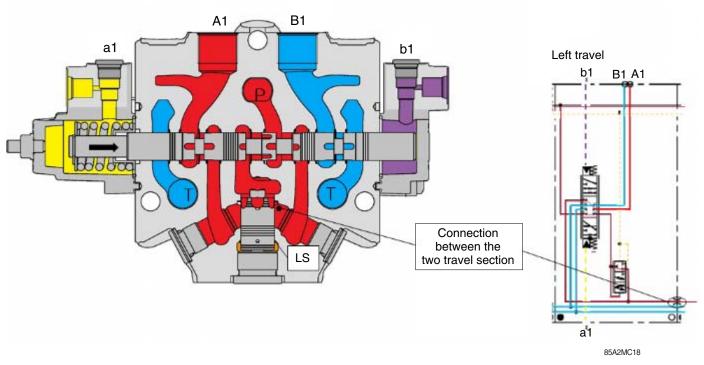
(2) Neutral position



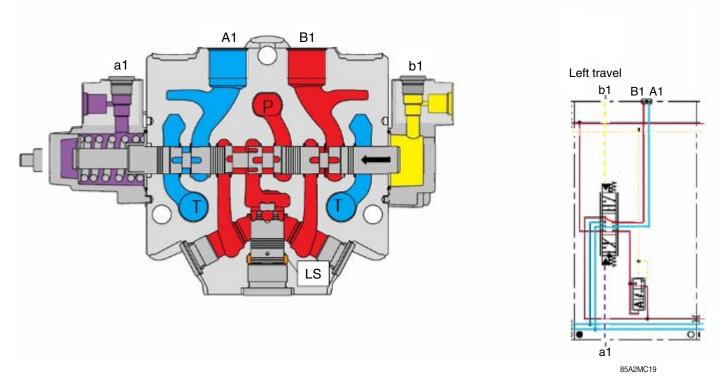
The spool is in neutral position, pump is in low pressure stand-by. The A and B ports are not connected to the pumps but to the tank. This is in order to ensure A and B to be drained to tank. The two translation branches, 1 and 2, are connected in order not to have differences in traction.



(3) Travel forward position



When the pilot pressure is led to the port a1, the oil from the pump flows to the cylinder port A1 and oil from the cylinder flows into the tank through the cylinder port B1.

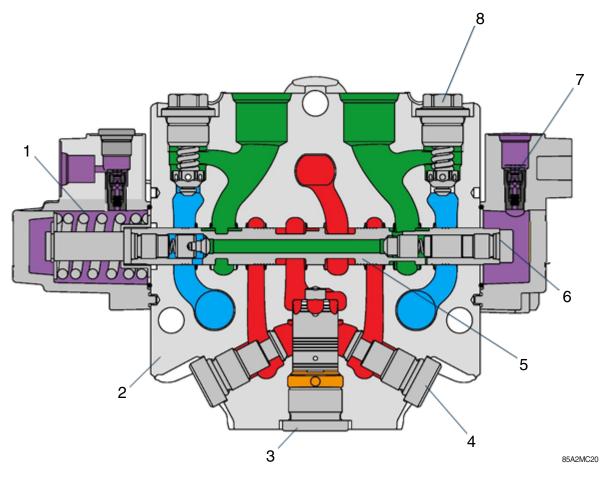


(4) Travel reverse position

When the pilot pressure is led to the port b1, the oil from the pump flows to the cylinder port B1 and oil from the cylinder flows into the tank through the cylinder port A1.

3) BOOM AND ARM SECTION 3 AND 5 DESCRIPTION - WITH REGENERATION SPOOLS

(1) Component description



Pump
Tank
Pilot
Pilot oil drain
LS pressure
Consumer
Regeneration flow (position PABT on nest pages)

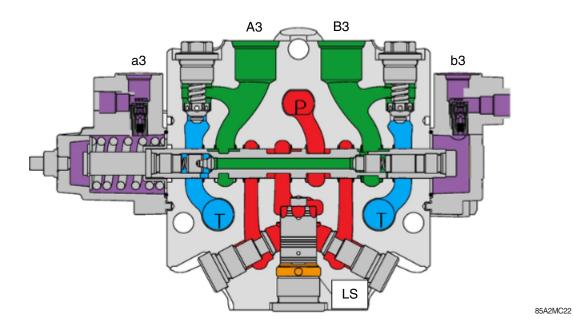
85A2MC21

- Spring pack
- 2 Housing

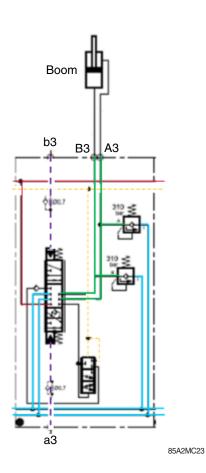
1

- 3 Pressure compensator
- 4 Check valves
- 5 Regeneration spool
- 6 Spool
- 7 Shuttle valve
- 8 Relief valves

(2) Neutral position

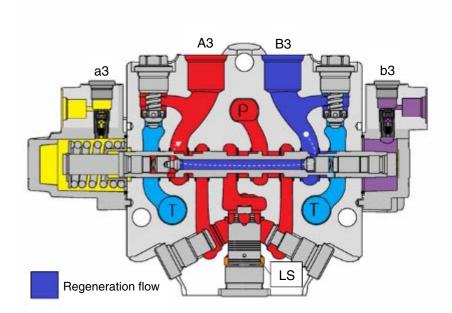


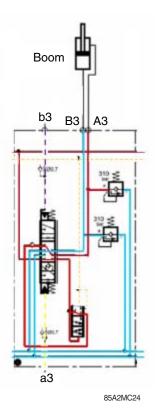
The spool is in neutral position, oil from the pump is blocked, pump is in low pressure stand-by. The A and B ports are not connected to the pump nor the tank.



(3) Boom section description

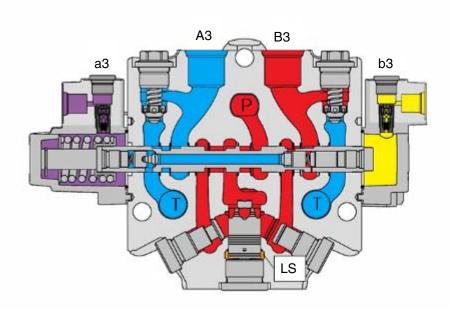
① Boom down position

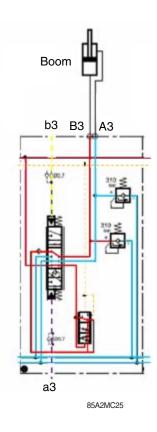




When the pilot pressure is led to the port a4, the oil from the pump flows to the cylinder port A4 and oil from the cylinder flows partially into the tank and partially trough regeneration path B to A through the cylinder port B4 .

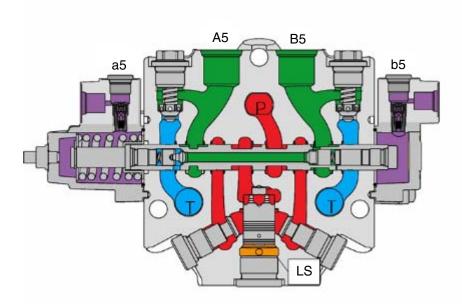


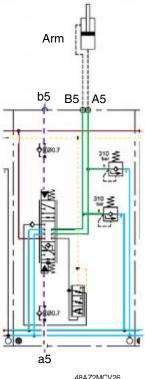




When the pilot pressure is led to the port b4, the oil from the pump flows to the cylinder port B4 and oil from the cylinder flows into the tank through the cylinder port A4.

(4) Arm section description ① Neutral position



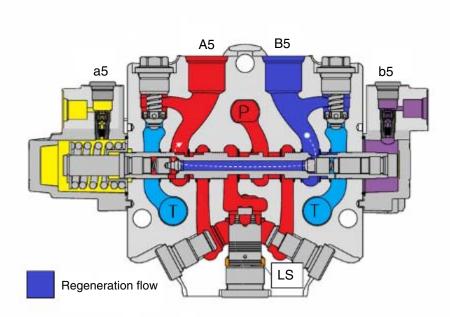


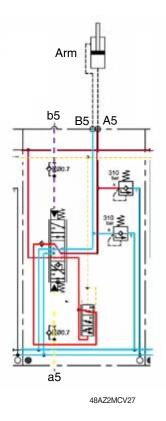
The spool is in neutral position, oil from the pump is blocked, pump is in low pressure stand-by. The A5 and B4 ports are not connected to the pump nor the tank.

48AZ2MCV26

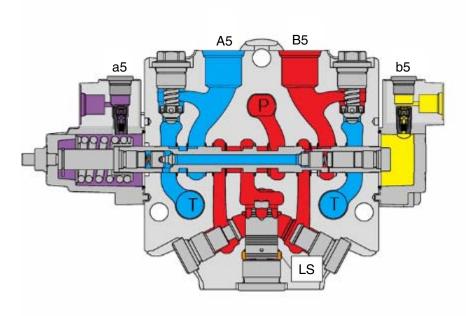
2 Arm roll in position

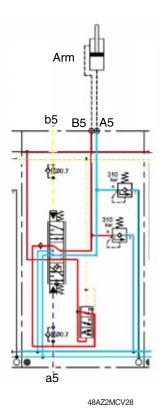
③ Arm roll out position





When the pilot pressure is led to the port a5, the oil from the pump flows to the cylinder port A5 and oil from the cylinder flows partially into the tank and partially trough regeneration path B to A through the cylinder port B5.

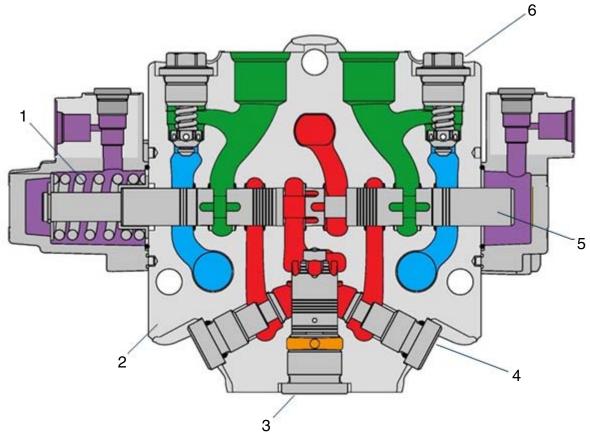




When the pilot pressure is led to the port b5, the oil from the pump flows to the cylinder port B5 and oil from the cylinder flows into the tank through the cylinder port A5.

4) BUCKET SECTION DESCRIPTION - SECTION 6

(1) Component description



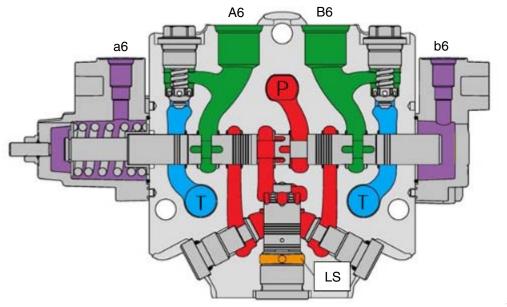
85A2MC29

- 1 Spring pack
- 2 Housing
- 3 Pressure compensator
- 4 Check valves
- 5 Spool
- 7 Overload relief valves

Pump
Tank
Pilot
Pilot oil drain
LS pressure
Consumer

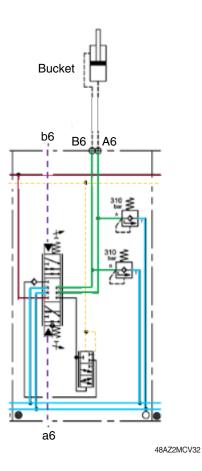
85A2MC30

(2) Neutral position

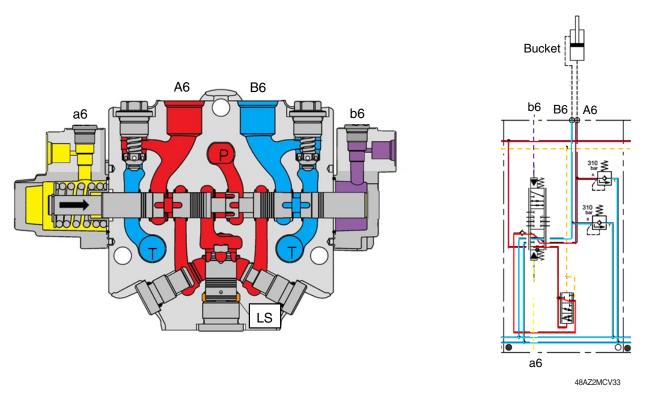


48AZ2MCV31

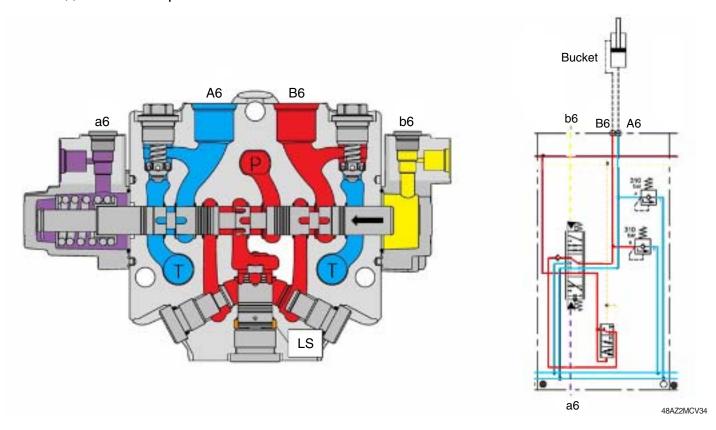
The spool is in neutral position, pump is in low pressure stand-by. The A6 and B6 ports are not connected to the pumps nor the tank.



(3) Bucket roll in position



When the pilot pressure is led to the port a6, the oil from the pump flows to the cylinder port A6 and oil from the cylinder flows into the tank through the cylinder port B6.

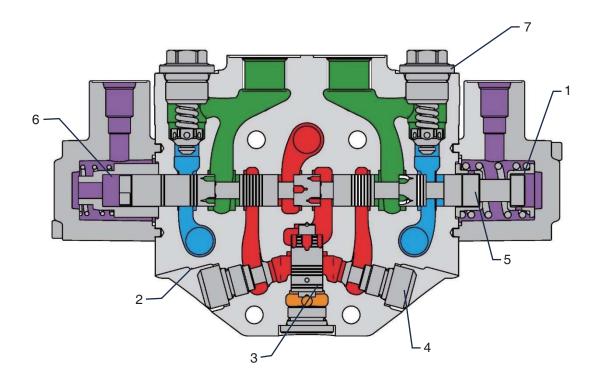


(4) Bucket roll out position

When the pilot pressure is led to the port b6, the oil from the pump flows to the cylinder port B6 and oil from the cylinder flows into the tank through the cylinder port A6.

5) DOZER SECTION DESCRIPTION - SECTION 7

(1) Component description

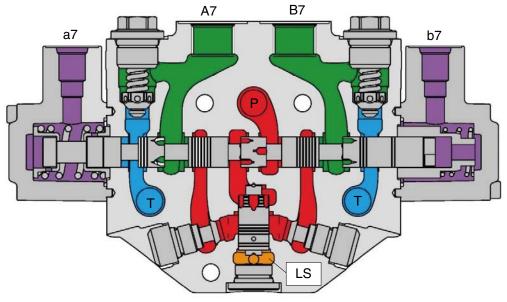


85A2MC35

			1	Spring pack
	Pump		2	Housing
			3	Pressure compensator
	Tank		4	Check valves
			5	Spool
	Pilot oil		6	Fourth position spring pack
			7	Relief valves
	Pilot oil drain			
	LS pressure			
	Consumer	48AA2MC43		

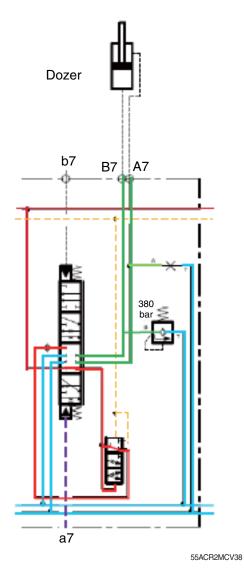
* This particular slide has a four position spool: neutral, PABT, PBAT and floating position.

(2) Neutral position

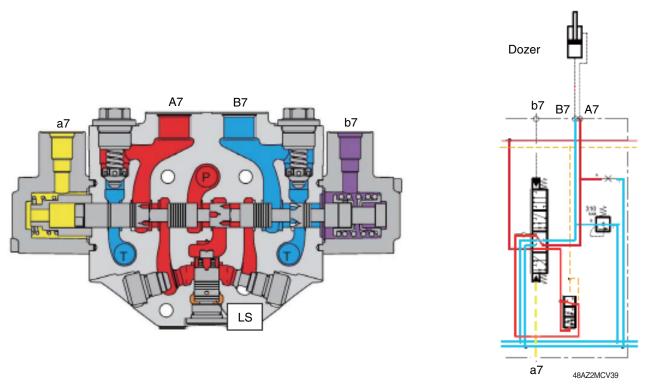


48AZ2MCV37

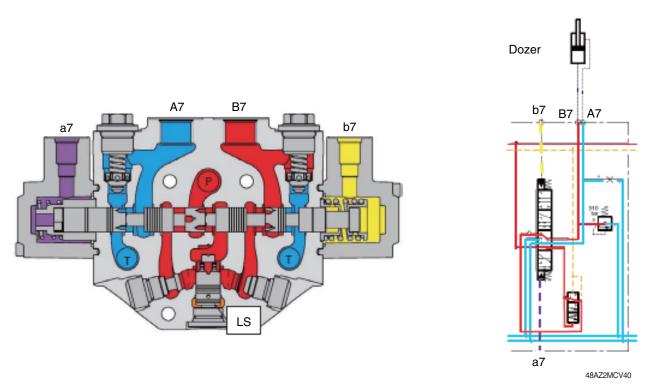
The spool is in neutral position, oil from the pump is not connected to the A7 or to the B7 ports. Pump is in low pressure stand-by.



(3) PABT position (dozer up)



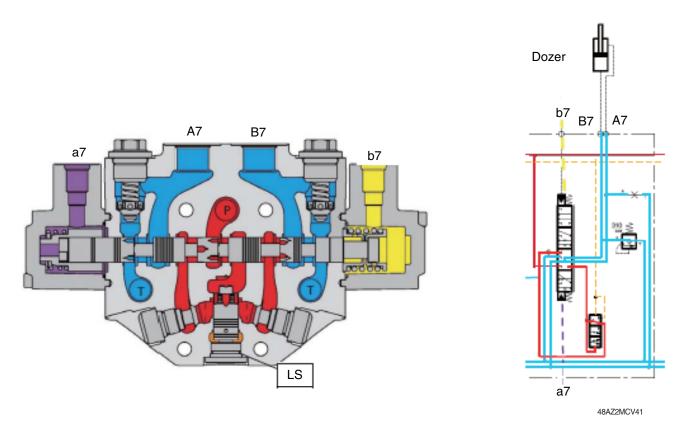
When the pilot pressure is led to the port a7, the oil from the pump flows to the cylinder port A7 and oil from the cylinder flows into the tank through the cylinder port B7.



(4) PBAT position (dozer down)

When the pilot pressure is led to the port b7, the oil from the pump flows to the cylinder port B7 and oil from the cylinder flows into the tank through the cylinder port A7.

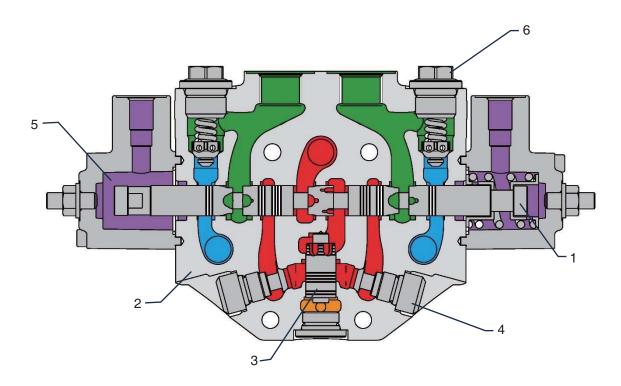
(5) Floating position



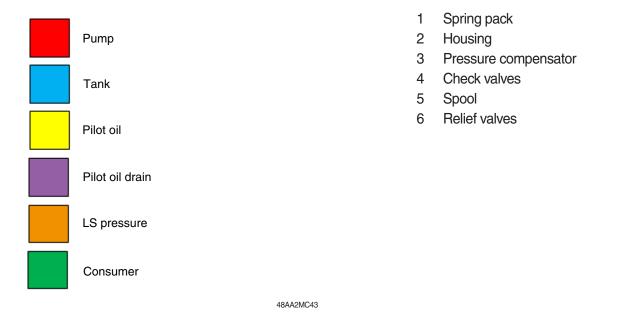
When the pilot pressure is led to the port b6 to maximal pressure, the spool is in the forth position, floating. The pump is in low pressure stand-by while A7 and B7 are connected to tank.

6) SLICES DESCRIPTION 8 : BOOM SWING

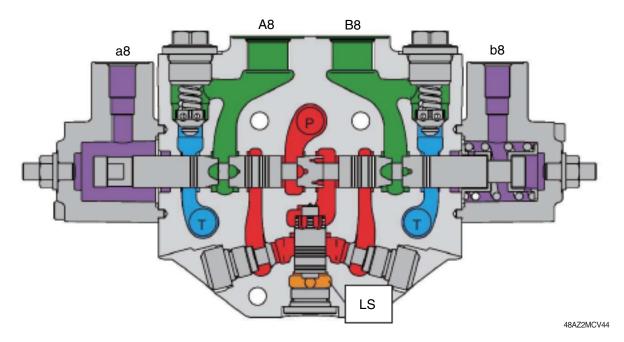
(1) Component description



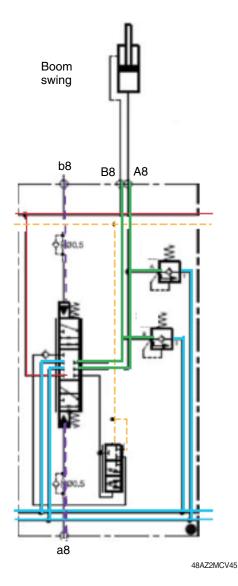
85A2MC42



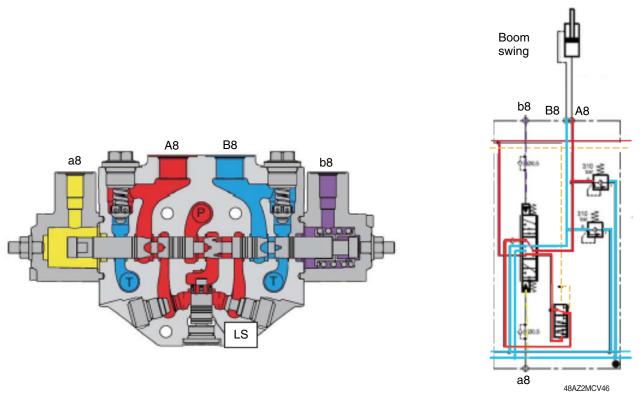
(2) Neutral position



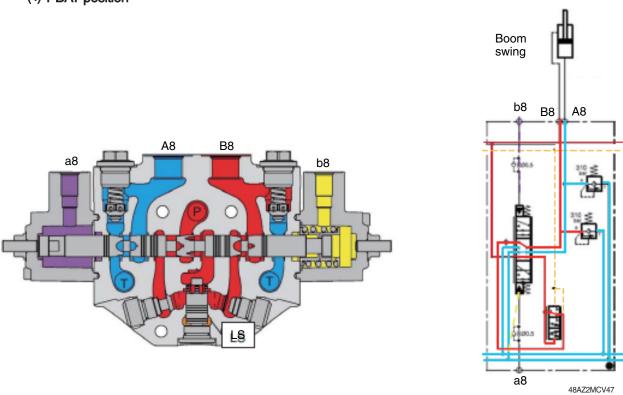
The spool is in neutral position, pump is in low pressure stand-by. The A8 and B8 ports are not connected to the pumps nor the tank.



(3) PABT position



When the pilot pressure is led to the port a7, the oil from the pump flows to the cylinder port A7 and oil from the cylinder flows into the tank through the cylinder port B7.

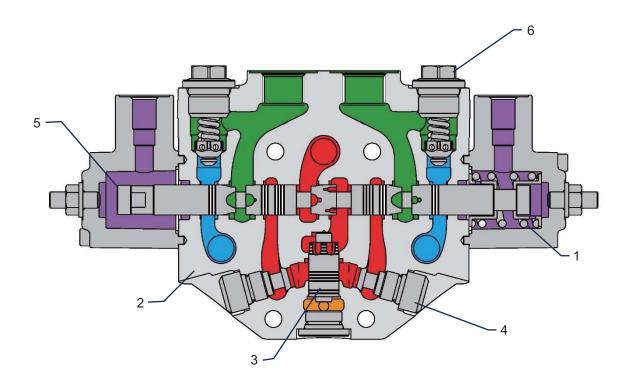


(4) PBAT position

When the pilot pressure is led to the port b7, the oil from the pump flows to the cylinder port B7 and oil from the cylinder flows into the tank through the cylinder port A7.

7) SLICES DESCRIPTION 9 : AUX 1

(1) Component description

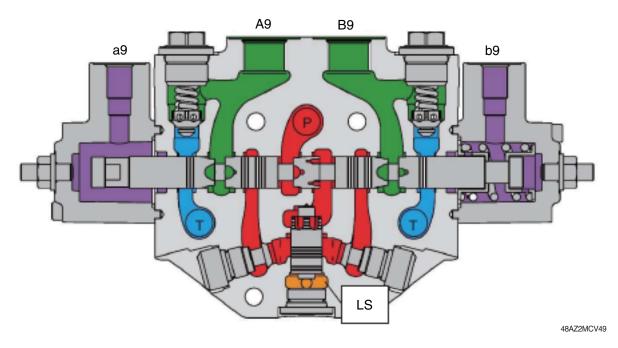


85A2MC48



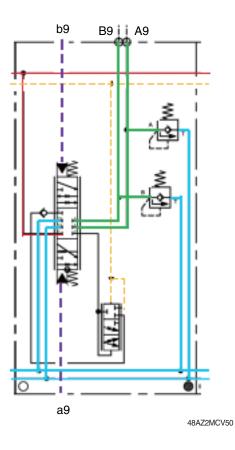
48AA2MC43

(2) Neutral position



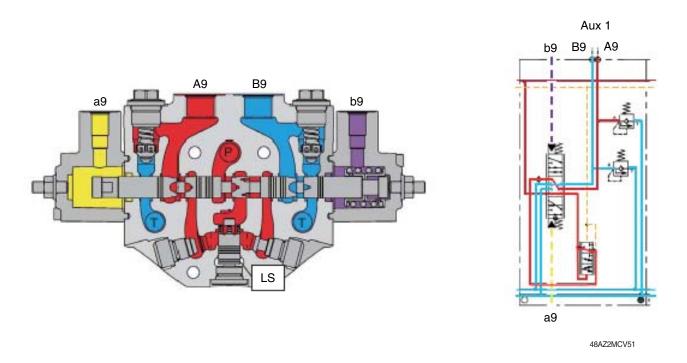
Aux 1

The spool is in neutral position, pump is in low pressure stand-by. The A9 and B9 ports are not connected to the pumps nor the tank.

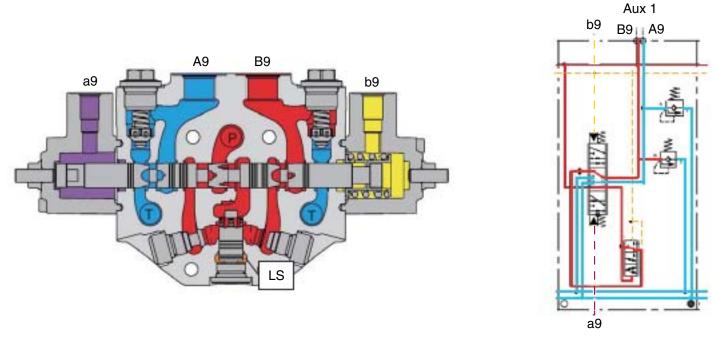


(3) PABT position

(4) PBAT position



When the pilot pressure is led to the port a9, the oil from the pump flows to the cylinder port A9 and oil from the cylinder flows into the tank through the cylinder port B9.



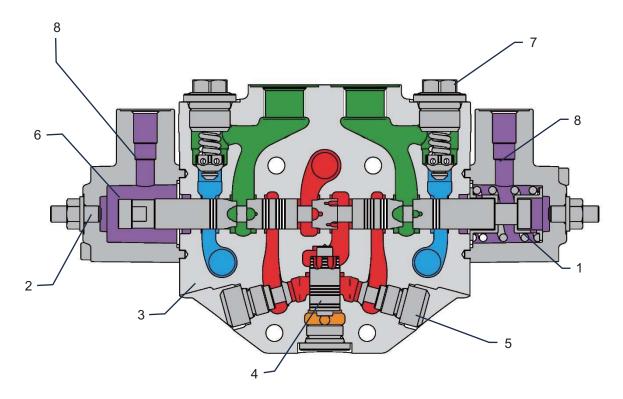
48AZ2MCV52

When the pilot pressure is led to the port b9, the oil from the pump flows to the cylinder port B9 and oil from the cylinder flows into the tank through the cylinder port A9.

2-39

8) SWING SLICE DESCRIPTION

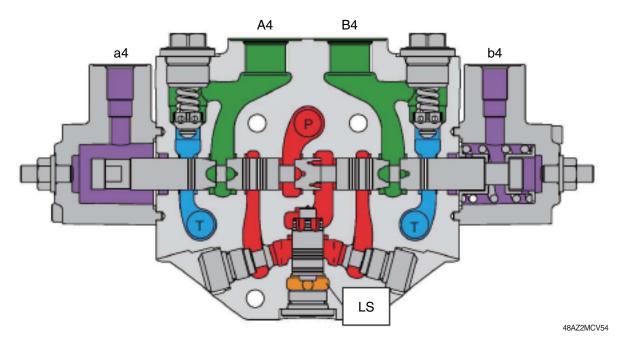
(1) Component description



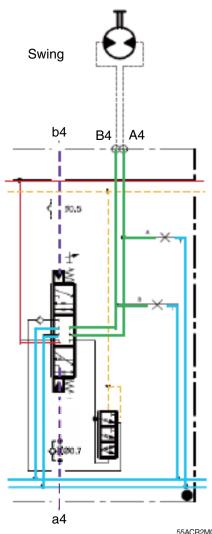
85A2MC53



(2) Neutral position

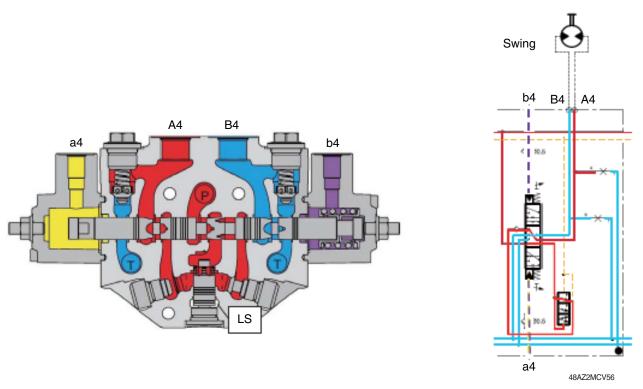


The spool is in neutral position, pump is in low pressure stand-by. The A4 and B4 ports are not connected to the pumps nor the tank. This slice is equipped with spool stroke limiters

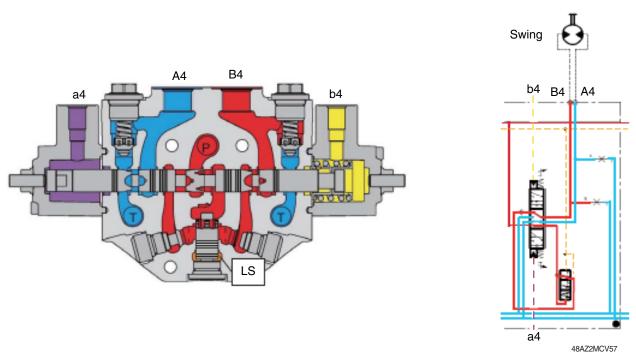


55ACR2MCV55

(3) PABT position



When the pilot pressure is led to the port a4, the oil from the pump flows to the motor port A4 and oil from the cylinder flows into the tank through the motor B4.



(4) PBAT position

When the pilot pressure is led to the port b4, the oil from the pump flows to the motor port B4 and oil from the cylinder flows into the tank through the motor port A4.

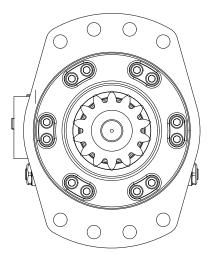
GROUP 3 SWING DEVICE

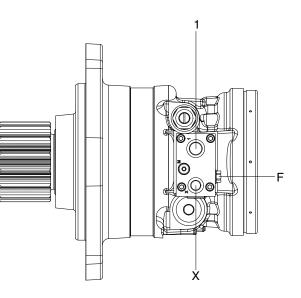
1. STRUCTURE

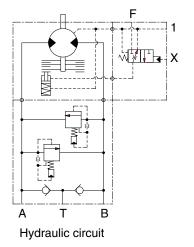
Swing device consists swing motor and swing reduction gear.

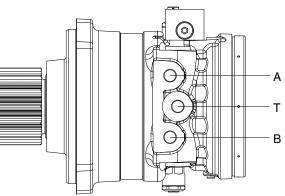
1) SWING MOTOR

Swing motor include mechanical parking valve, relief valve and make up valve.





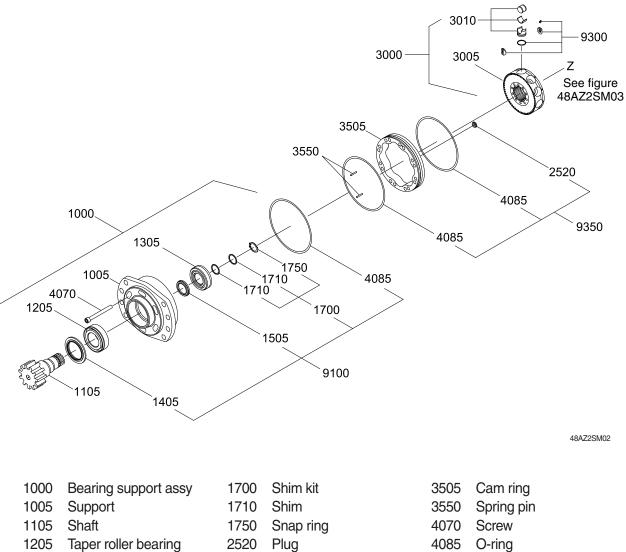




48AZ2SM01

Port	Port name	Port size	
Α	Main port	PF 3/8	
В	Main port	PF 3/8	
1	Drain port	PF 3/8	
X	Pilot port	PF 1/4	
Т	Make up port	PF 3/8	
F	Brake release port	PF 1/4	

2) COMPONENTS (1/2)



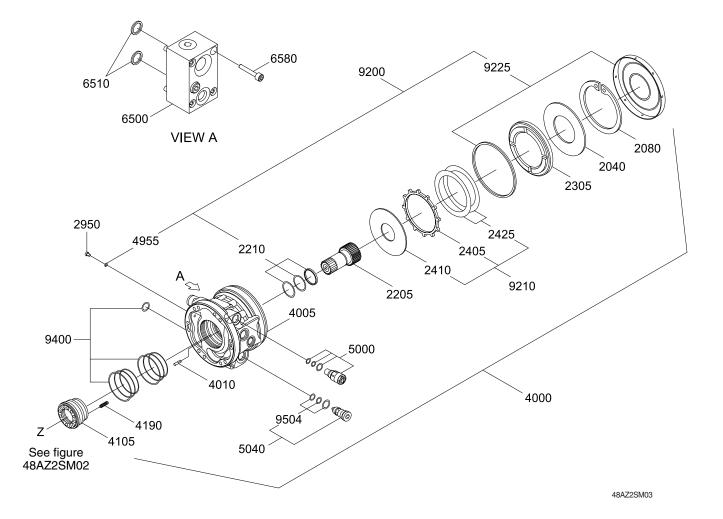
1405 Seal ring 1505 Oil seal

Taper roller bearing

1305

- 3000 Cylinder block assy3005 Block3010 Piston kit
- 4070 Screw
 4085 O-ring
 9100 Seal kit
 9300 Piston service kit
 9350 Seal kit

COMPONENTS (2/2)

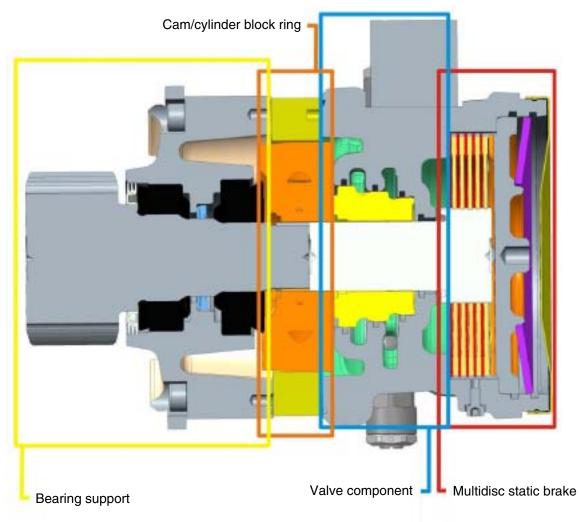


2040	Spring washer
2080	Snap ring
2205	Brake shaft
2210	Seal kit
2305	Brake piston
2405	External disc
2410	Internal disc
2425	Shim kit
2950	Screw

4000	Brake valve housing assy
4005	Housing
4010	Roll pin
4105	Brake valve
4190	Spring
4955	O-ring
5000	Release valve
5040	Check valve

6500	Brake valve
6510	O-ring
6580	Screw
9200	Brake service kit
9210	Brake service kit
9225	Brake cover kit
9400	Seal kit
9504	Seal kit

2. MAJOR PARTS

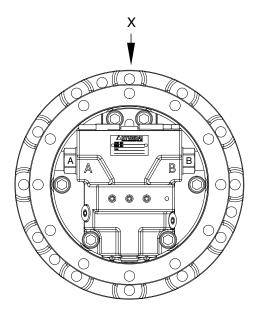


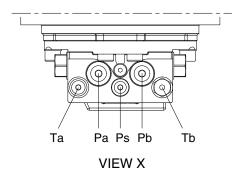
48AZ2SM04

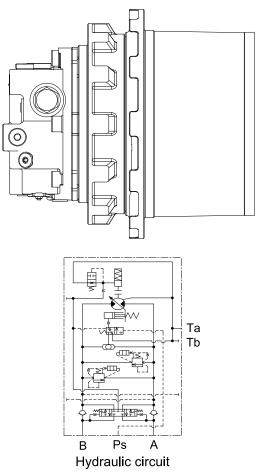
GROUP 4 TRAVEL DEVICE

1. CONSTRUCTION

Travel device consists travel motor and gear box. Travel motor includes brake valve, parking brake and high/low speed changeover mechanism.



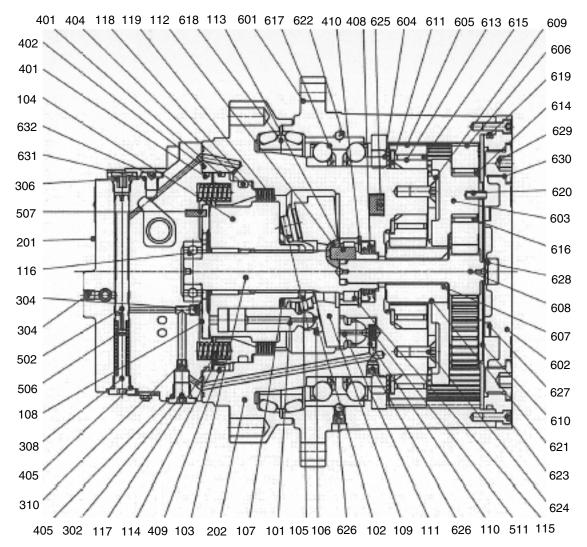




55ACR2TM01

Port	Port name	Port size	
Pa	Main port	PF 1/2	
Pb	Main port	PF 1/2	
a1, a2	Gauge port	PT 1/4	
Ta, Tb	Drain port	PF 3/8	
Ps	2 speed control port	PF 1/4	

1) STRUCTURE (1/2)



48AZ2TM02

O-ring

Bolt

Snap ring

Socket bolt

Side plate A

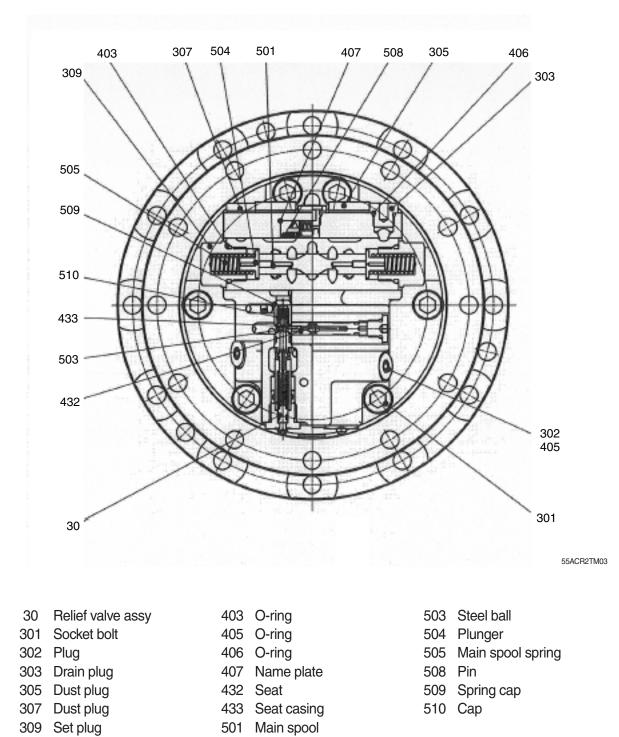
- 101 Piston
- 102 Shoe
- 103 Drive shaft
- 104 Cylinder block
- 105 Spherical bushing
- 106 Set plate
- 107 Cylinder spring
- 108 Valve plate
- 109 Swash plate
- 110 Swash piston
- 111 Swash shoe
- 112 Pivot
- 113 Pivot pin
- 114 Brake piston
- 115 Roller bearing
- 116 Ball bearing
- 117 Brake spring
- 118 Friction plate 119 Separator plate 201 Valve casing 202 Casing 302 Plug 304 NPTF plug 306 Dust plug 308 2 speed plug 310 Restrictor 401 O-ring 402 O-ring 404 O-ring 408 Oil seal 409 Back up ring 410 Snap ring

502 2 speed spool

506 Spring

- 507 Spring pin 617 Angular bearing 511 Spring 618 Floating seal kit 601 Housing 619 602 Cover 620 Spring pin 603 Holder 621 604 Ring nut 622 Steel ball 605 Planetary gear F 623 606 Planetary gear R 624 607 Sun gear 625 Plug 608 Ring nut 626 Plug 609 Thrust plate F 627 610 Thrust plate R 628 Side plate B 611 Thrust washer 629 Plug 613 Collar 630 O-ring 614 Inner race 631 O-ring 615 Needle bearing 632 Plug 616 Needle bearing
- 2 48

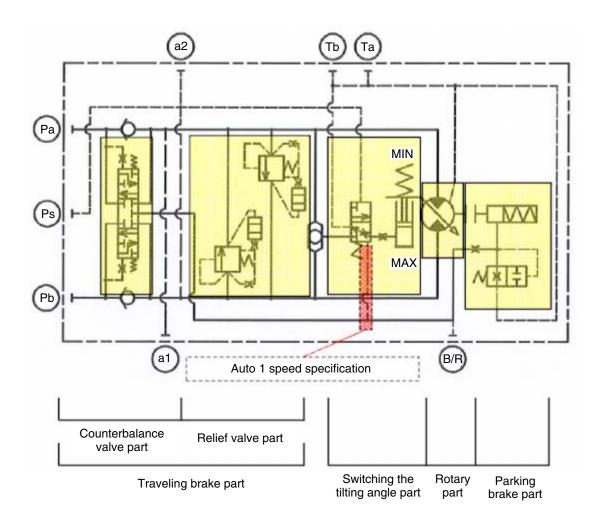
STRUCTURE (2/2)



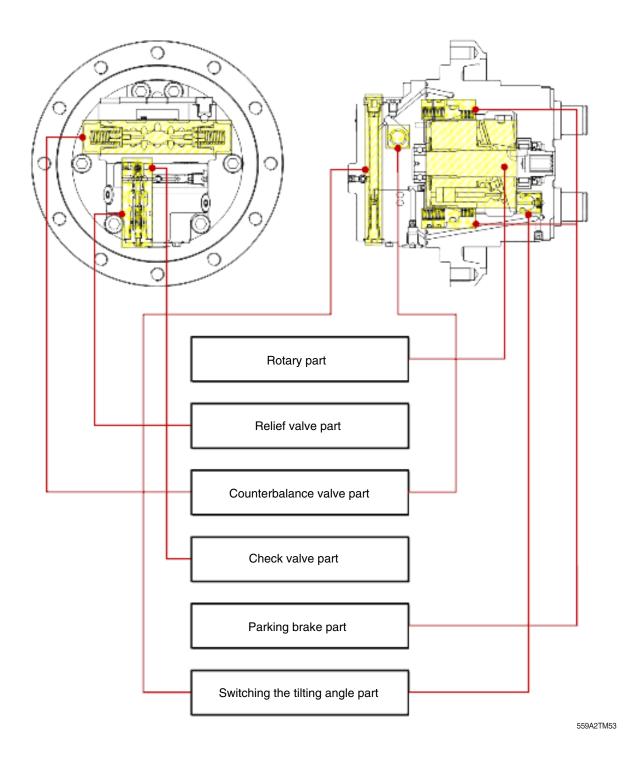
2) MAJOR COMPONENT

This product is only composed of hydraulic motor. Reduction parts are not composed. This hydraulic motor is variable swash plate axial piston motor. It is composed of 4 parts.

- Rotary part which makes rotatory power
- Traveling brake valve part
- Parking brake part
- Switching the tilting angle part (auto 1/2 speed control part)



3) BASIC STRUCTURE



2. WORKING PRINCIPLE

1) HYDRAULIC MOTOR SECTION

When high pressure oil passes from pump through the inlet port of the valve plate(108) and flows into the cylinder (104) as shown in figure, the oil pressure acts upon the piston (101) to generate the axial force "F". The force "F" acts on the swash (109) plane in the axial direction.

 $F = P \times A$ (P : Pressure, A : Area)

The swash plate (109) is fixed with an inclination angle of α to the axis of the drive shaft (103). Therefore, this force is divided into two vector forces through the shoe (102) : namely, the force F1 vertical to the swash plate (109) and the force F2 perpendicular to the drive shaft (103).

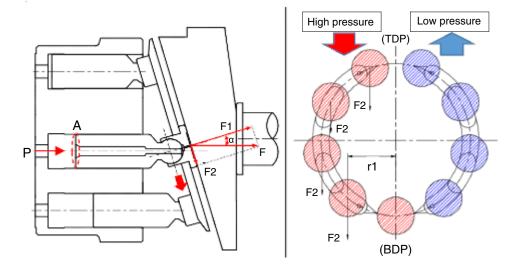
Because of the force "F2", piston (101) slides along with shoe (102) in the direction of the arrow in Figure. This force "F2" is transmitted to the cylinder block (104) via the piston (101) and generates a couple of forces which turn the output drive shaft (103).

In the cylinder block (104) nine pistons are equispaced and the pistons connected to the high pressure oil inlet ports give their rotating torque to the output shaft sequentially.

When the oil inflow/outflow direction are reversed, the rotating direction of the output shaft is reversed.

The theoretical output torque "T [N/m]" is given by the flowing.

 $T = \frac{P \times q}{2\pi}$ P : Effective pressure difference (Mpa), q : Displacement per revolution (cm³)



2) TRAVELING BRAKE VALVE

Traveling brake valve is composed of relief valve, counterbalance valve and check port A is connected with hydraulic pump and port B is connected with tank.

(1) In case of traveling

When the compressed oil, which is supplied along the inlet port, exceeds certain pressure, it pushes cap (509). And, it is supplied to one side of the casing (202).

It is trying to rotate the hydraulic motor.

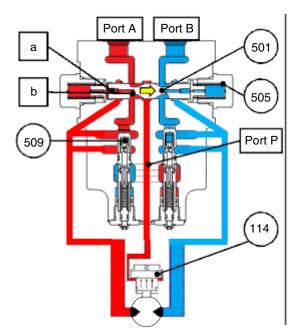
At the same time, the compressed oil enters the chamber {a} along small hole {b} of main spool (501) and acts on the face of main spool (501). After increasing pressure of oil, when this pressure exceeds the spring elasticity force of main spool spring (505), main spool (501), which is held in neutral by the spring elasticity force, moves to the right.

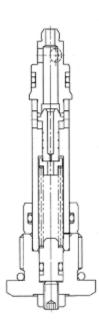
The inlet side and outlet side that was blocked by main spool (501) during stop connect with each other. So, return oil returns to the oil tank, so the hydraulic motor rotates.

Furthermore as main spool (501) moves, the path of parking brake (port P) is connected.

When compressed pressure, which enter to (port P), becomes brake release pressure, it operates brake piston (114) and parking brake is released.

If the direction of oil inlet is reversed, main spool (501) and check valve motion is reversed. Output rotation direction is also reversed.





(2) In case of stop

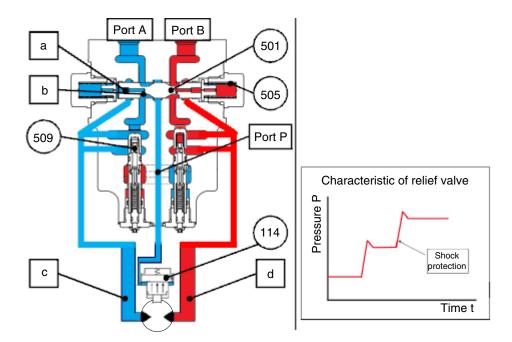
If the pressure supplied along the port to the inlet breaks while traveling, the pressure applied to the section of the main spool (501) is removed. Therefore, the main spool (501), which was pushed to the right, returns to neutral due to the spring elasticity force of the main spool spring (505).

The rotary part continues to rotate under inertia even if pressure is lost from the inlet side. As the main spool (501) returns to neutral, the connected inlet and outlet sides of the flow path are blocked. Since there is no escape location for the returned oil, the pressure of the exit side (D) is raised.

The returned oil with increased pressure enters the relief valve (30). if it exceeds the set pressure of the relief valve (30), operates the relief valve (30). The flow path from the outlet side $\{D\}$ to the inlet side $\{C\}$ is connected. And it controls the pressure on the outlet side.

At the same time it prevents cavitation on the inlet side.

It also relieves the shock during stop while controlling pressure on the outlet side with relief valve (30) in two stages, and apply soft braking to the hydraulic motor by applying an orifice and notch on the main spool (501).

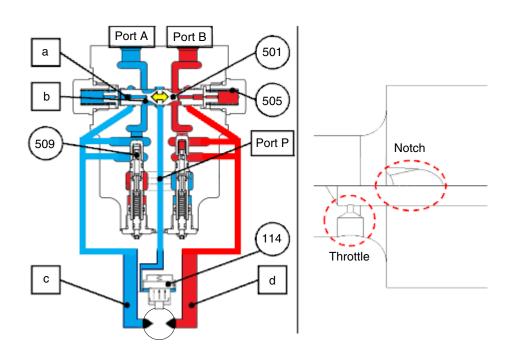


(3) In case of overrun

Overrun is when the excavator's speed is increased by the it's gravity (inertia), such as when an excavator is going downhill, causing the hydraulic motor to rotate above the supply flow of the hydraulic pump.

In the case of overrun, the compressed oil on the inlet side is entered into the rotary and the pressure on the inlet side is reduced. Therefore, due to the spring elasticity force of the main spool spring (505), main spool (501) returns to neutral, as it stops.

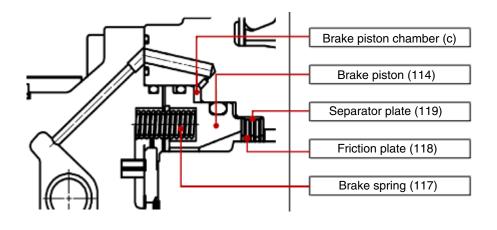
At the same time, back pressure is generated due to the throttle (notch of main spool) between the outlet side (D) and the outlet port (port B) passage. The back pressure controls the return speed of the main spool (501) and hydraulic motor, which is about to be rotated by inertia forces, is decelerated. The operation of main spool (501) is controlled by the notch of main spool (501) and throttle. So motor smoothly moves according to the supply flow rate.



3) PARKING BRAKE

The parking brake is wet-type multiple disk brakes. It is a negative brake system which is released when the brake release pressure enters the brake piston chamber.

The internal structure of parking brake is shown in figure. Friction plate (118) and separator plate (119) are alternately stacked, and acting on springs to produce brake torque with friction forces. It prevents not only the braking of excavators but also overrun or slip during traveling and stopping on the slip.



559A2TM58

(1) In case traveling

The cylinder block (104) is connected to the drive shaft (103) with spline. In addition, the separator plate (119) is restrained from circumferentially-rotating by an arc groove cut on the casing (202).

The friction plate (118) which is connected to the arc groove cut on cylinder block (104), can be rotated along the cylinder block (104).

When pressurized oil is supplied from the inlet side during traveling operation, the blocked flow path is opened. so pressurized oil is supplied to the brake piston chamber (c) that is comprised inside brake piston (114) and casing (202).

If the hydraulic force F4 of the brake piston chamber (c) is greater than the spring elasticity force F3 of the brake spring (117), then brake piston (114) move to valve casing. (above brake release pressure)

F3 = k x n , k : Spring constant, x : Spring stroke, n : Number of spring brake

F4 = P × (A1 - A2), P : Main pressure of input, (A1 - A2) : Area difference of brake piston

The force that friction plate (118) and separator plate (119) pressurize the casing (202) disappears and the brake releases.

So, the hydraulic motor can rotate.

(2) In case of stop

If the pressurized oil supplied by the inlet is cut off during stop, the pressurized oil supplied to the brake piston chamber (c) will also be blocked. (below brake release pressure)

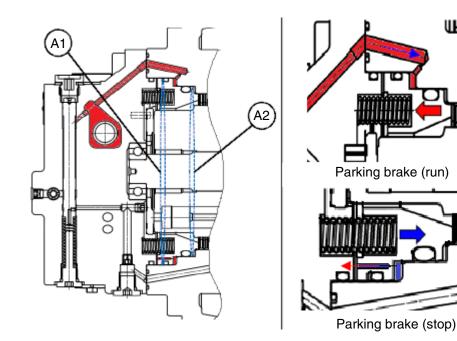
If the spring elasticity force F3 of the brake spring (117) is greater than the hydraulic force F4 of the brake piston chamber (c), then brake piston (114) move to casing by spring elasticity force. The hydraulic oil of the brake piston (114) is drained through the throttle. Therefore brake piston (114) smoothly operates.

F3 < F4

 $F3 = k \times n$, k : Spring constant, x : Spring stroke, n : Number of spring brake

 $F4 = P \times (A1 - A2)$, P : Main pressure of input, (A1 - A2) : Area difference of brake piston

When the brake piston (114) pushes casing (202) by the brake spring (117), the frictional force appears between friction plate (118), casing (202), separator plate (119) and brake piston (114). parking brake appears by friction force and spring elasticity of the brake spring (117), the drive shaft (103) is constrained.



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¶⊢

4) 1/2 SPEED SWITCHING OPERATION (AUTOMATIC 1/2 SPEED CONTROL PART)

(1) Low speed traveling

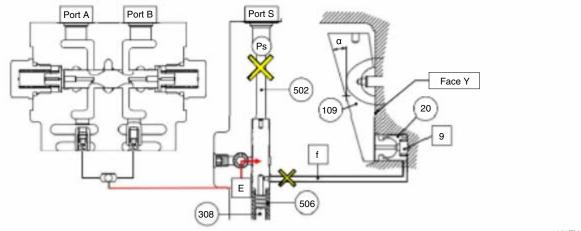
If pilot pressure is not supplied on pilot port (port S), 2 speed spool (502) is pushed in the direction of the port S by spring elasticity of 2 speed spool spring (506).

As a result, the compressed oil from the high pressure selection check valve (E) is not connected to the swash piston chamber (g).

The compressed oil of swash piston chamber{g} is drained through the flow path of 2 speed spool chamber (f).

So, the compressed oil from the high pressure selection check valve (E) is not connected to the swash piston chamber {g}. As a result, the swash plate (109) will be the maximum angle α and the stroke of the piston (101) will be long. So, a large amount of oil will be required for rotating the motor once.

Therefore the displacement of the hydraulic motor is maximized and rotated at low speed.



(2) High speed traveling

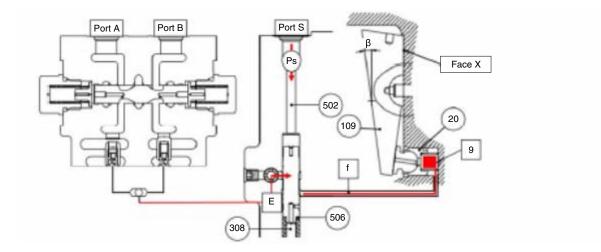
If the pilot pressure (20~50 kgf/cm²) is supplied to the port (port S), the pilot pressure overcomes the oil pressure in the main port and the spring elasticity force of the 2 speed spool spring (506). and it pushes the 2 speed spool (502) to the 2 speed plug (308) direction.

This is why the pressure from the high pressure selection check valve (E) is connected to the flow path (f).

The pressurized oil flows into the $\{g\}$ chamber along the flow path $\{f\}$ and pushes swash piston (20) to contact the face 'X' of swash plate (109) with the wall of the casing (202).

As a result, the swash plate (109) is the minimum angle β . Because stroke of piston (101) is shortened, a small amount of oil is used for one revolution.

Therefore, the displacement of the hydraulic motor is minimized and is rotated at high speed.



(3) Automatic 1/2 speed control part

If the load is increased during the 2-speed driving, the hydraulic pressure on the main port is increased. The pressure ($\triangle P$) of main port and spring elasticity force of 2 speed spool spring (506) will overcome the pressure of pilot, 2 speed spool (502) is pushed in port S direction.

 $F5 < [{F6 \times (A4 - A3)} + (Fspring)]$

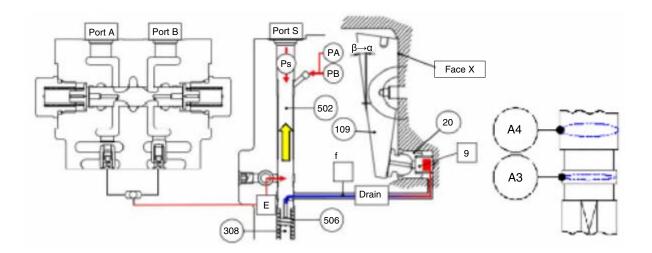
 $F5 = PS \times A3$, PS : Pilot pressure, A3 : 2 speed spool area

 $F6 = (PA \text{ or } PB) \times (A4 - A3), (PA \text{ or } PB) :$ Main pressure difference between inlet side and outlet side Fspring = K x X ; K : Spring constant of 2 speed spool spring, X : Spring stroke

Therefore, flow path from the high pressure selection check valve (E) to (f) is blocked.

And the pressure of (g) is slowly drained to 2 speed spool chamber (f) through throttle and a notch of 2 speed spool.

The angle of swash plate (109) transfers from β to α , and the motor automatically switches from 2 speed to 1 speed to rotate at low speed.



5) REDUCTION GEAR



559A2TM63

- (1) Refer to the section drawing for the basic construction.
- (2) The reduction gear consists of two stage planetary gears.
- (3) The reduction ratio is determined by the number of teeth of the gear, and the reduction ratio is 42.439.

In other words, the number of revolutions of the hydraulic motor is transmitted to the output shaft at 1 / reduction ratio.

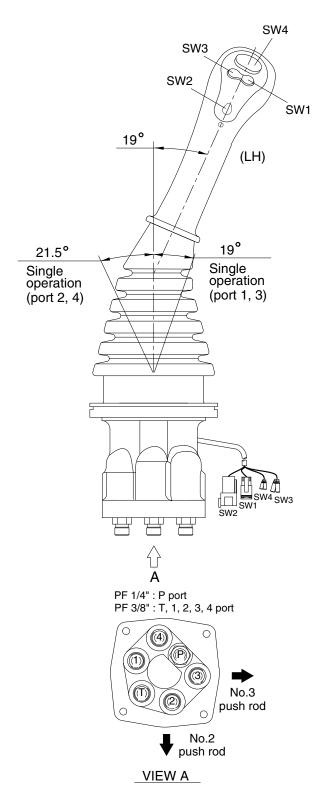
(4) The direction of rotation of the input and output shafts is opposite.

GROUP 5 RCV LEVER

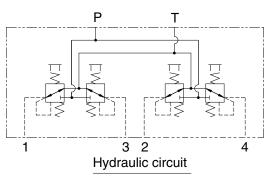
TYPE 1 (KPM, LH)

1. STRUCTURE

The casing has the oil inlet port P (primary pressure) and the oil outlet port T (tank). In addition the secondary pressure is taken out through ports 1,2,3 and 4 provided at the bottom face.

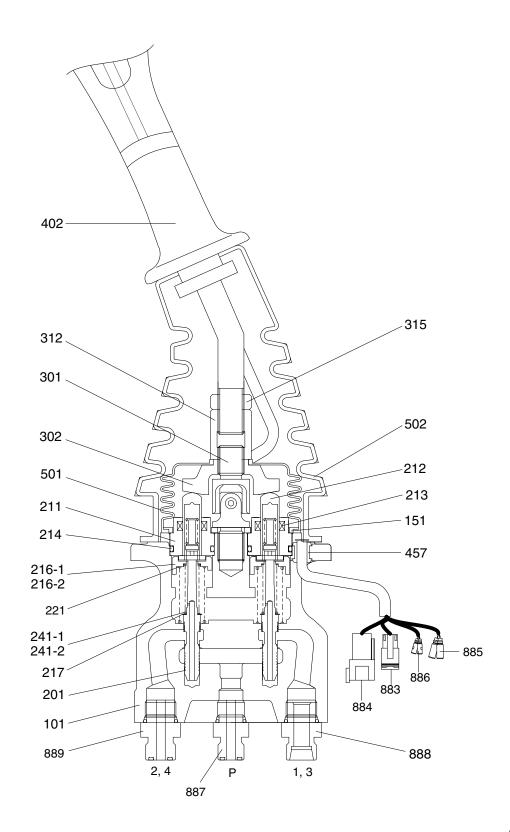


Switches		
Switch no.	Color (LH)	
SW1	Gray	
SW2	Blue	
SW3	Black	
SW4	Red	



55ACR2RL01

Port	LH	Remark	
Р	Pilot oil inlet port		
Т	Pilot oil return port		
1	Left swing port	PF 1/4	
2	Arm out port		
3	3 Right swing port		
4	Arm in port		



55ACR2RL02

CROSS SECTION

The construction of the pilot valve is shown in the attached cross section drawing. The casing has vertical holes in which reducing valves are assembled.

The pressure reducing section is composed of the spool (201), spring (221-1, 221-2) for setting secondary pressure, return spring (221), spring seat (216-1, 216-2) and spring seat (217). The spring for setting the secondary pressure has been generally so preset that the secondary pressure is 7.6 to 20.4 kgf/cm². The spool is pushed against the push rod (212) by the return spring.

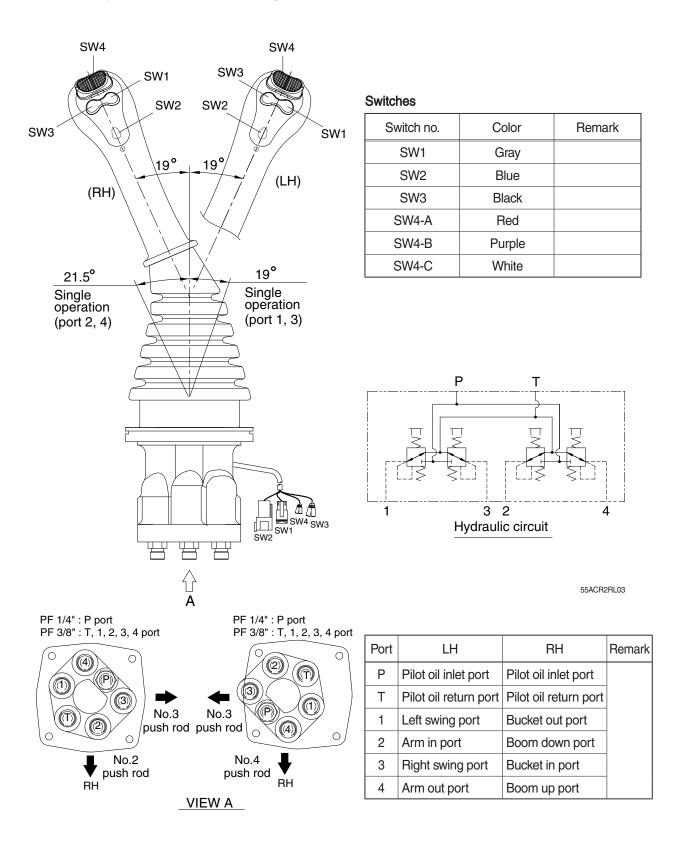
When the push rod is pushed down by tilting the handle, the spring seat comes down simultaneously and changes setting of the secondary pressure spring.

101	Case	221	Spring	501	Bellows
151	Plate	241-1	Spring (port 1, 3)	502	Bellows
201	Spool	241-2	Spring (port 2, 4)	883	Terminal
211	Plug	246-1	Spring (port 1, 3)	884	Terminal
212	Push rod	246-2	Spring (port 2, 4)	885	Connector
213	Oil seal	301	Joint	886	Connector
214	O-ring	302	Plate	887	Connector
216-1	Spring seat (port 1, 3)	312	Adjust nut	888	Connector
216-2	Spring seat (port 2, 4)	315	Lock nut	889	Connector
217	Washer	402	Handle		
218	Spring seat	457	Bushing		

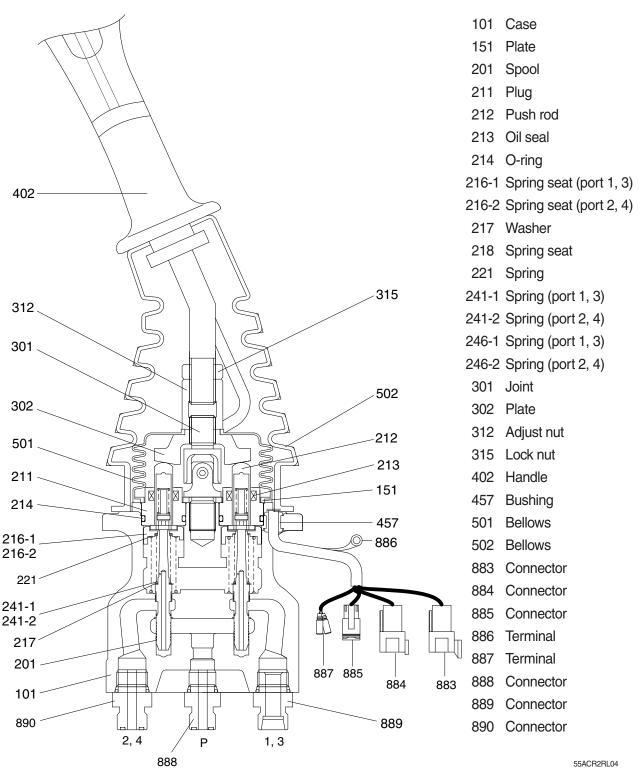
TYPE 2 (KPM)

1. STRUCTURE

The casing has the oil inlet port P (primary pressure) and the oil outlet port T (tank). In addition the secondary pressure is taken out through ports 1, 2, 3 and 4 provided at the bottom face.



CROSS SECTION



The construction of the pilot valve is shown in the attached cross section drawing. The casing has vertical holes in which reducing valves are assembled.

The pressure reducing section is composed of the spool (201), spring (241-1, 241-2) for setting secondary pressure, return spring (221), spring seat (216-1, 216-2) and washer (217). The spring for setting the secondary pressure has been generally so preset that the secondary pressure is 7.6 to 20.4 kg/cm². The spool is pushed against the push rod (212) by the return spring.

When the push rod is pushed down by tilting the handle, the spring seat comes down simultaneously and changes setting of the secondary pressure spring.

2. FUNCTIONS (KPM, Type 1 and 2)

1) FUNDAMENTAL FUNCTIONS

The pilot value is a value that controls the spool stroke, direction, etc of a main control value. This function is carried out by providing the spring at one end of the main control value spool and applying the output pressure (secondary pressure) of the pilot value to the other end.

For this function to be carried out satisfactorily, the pilot valve is composed of the following elements.

- (1) Inlet port (P) where oil is supplied from hydraulic pump.
- (2) Output ports (1, 2, 3 & 4) to apply pressure supplied from inlet port to ends of control valve spools.
- (3) Tank port (T) necessary to control the above output pressure.
- (4) Spool to connect output port to inlet port or tank port.
- (5) Mechanical means to control output pressure, including springs that work on the above spools.

2) FUNCTIONS OF MAJOR SECTIONS

The functions of the spool (11) are to receive the supply oil pressure from the hydraulic pump at its port P, and to change over oil paths to determine whether the pressure oil of port P is led to output ports 1, 2, 3 & 4 or the output port pressure oil to tank port T.

The spring (241-1) works on this spool to determine the output pressure.

The change the deflection of this spring, the push rod (212) is inserted and can slide in the plug (211).

For the purpose of changing the displacement of the push rod through the swash plate (302) and adjusting nut (312) are provided the handle (402) that can be tilted in any direction around the fulcrum of the universal joint (301) center.

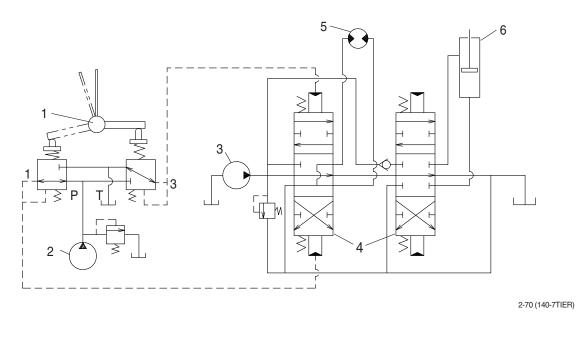
The spring (221) works on the case (101) and spring seat (216-1, 2) and tries to return the push rod (212) to the zero-displacement position irrespective of the output pressure, securing its resetting to the center position.

This also has the effect of a reaction spring to give appropriate control feeling to the operator.

3) OPERATION

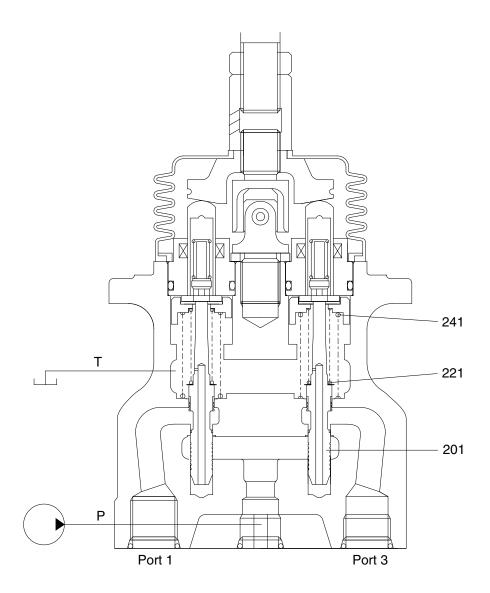
The operation of the remote control valve will be described on the basis of the hydraulic circuit diagram shown below and the attached operation explanation drawing.

The diagram shown below is the typical application example of the pilot valve.



- 1 Remote control valve
- 2 Pilot pump
- 3 Main pump
- 4 Main control valve
- 5 Hydraulic motor
- 6 Hydraulic cylinder

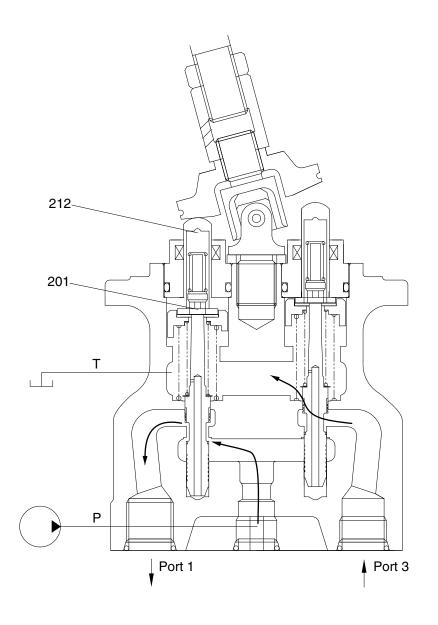
(1) Case where handle is in neutral position



55ACR2RL05

The force of the spring (241) that determines the output pressure of the pilot valve is not applied to the spool (201). Therefore, the spool is pushed up by the spring (221) to the position of port (1, 3) in the operation explanation drawing. Then, since the output port is connected to tank port T only, the output port pressure becomes equal to tank pressure.

(2) Case where handle is tilted



55ACR2RL06

When the push rod (212) is stroked, the spool (201) moves downwards.

Then port P is connected with port (1) and the oil supplied from the pilot pump flows through port (1) to generate the pressure.

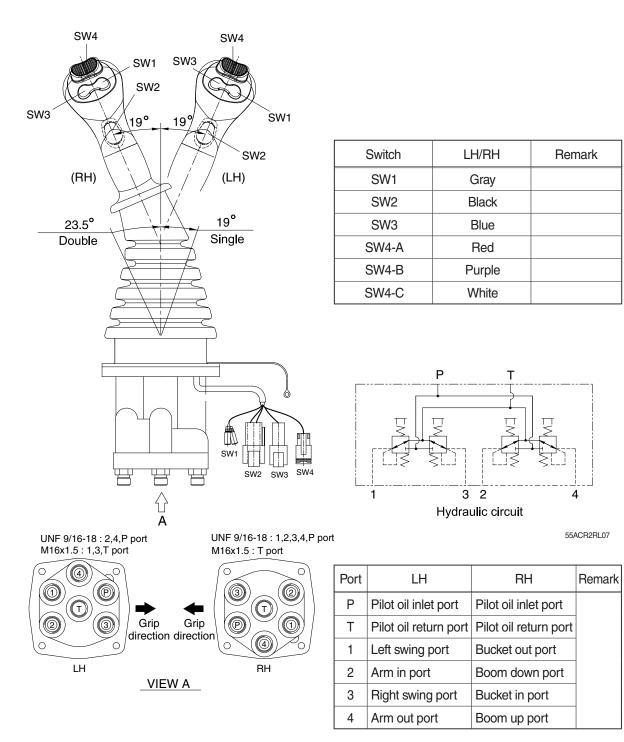
When the pressure at port (1) increases to the value corresponding to the spring force set by tilting the handle, the hydraulic pressure force balances with the spring force. If the pressure at port (1) increases higher than the set pressure, port P is disconnected from port (1) and port T is connected with port (1). If it decreases lower than the set pressure, port P is connected with port (1) and port T is disconnected from port 1.

In this manner the secondary pressure is kept at the constant value.

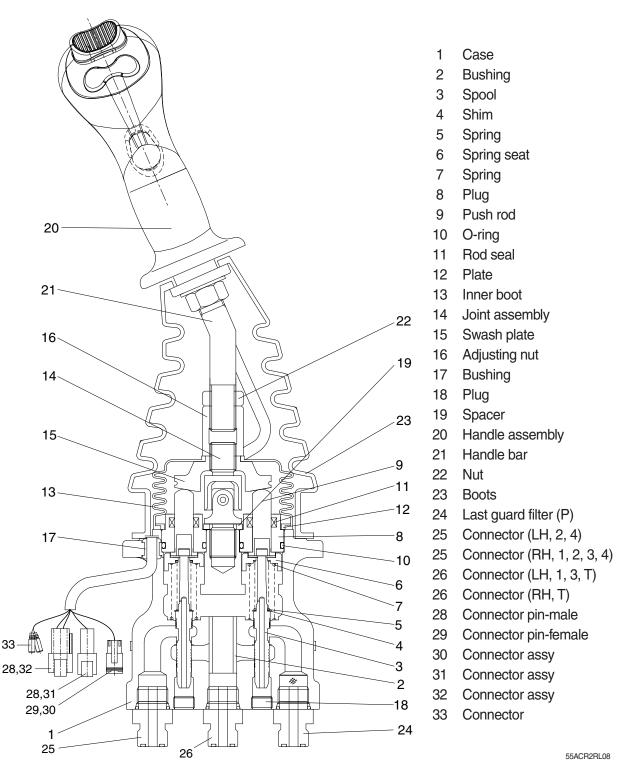
TYPE 3 (DANFOSS)

1. STRUCTURE

The casing has the oil inlet port P (primary pressure) and the oil outlet port T (tank). In addition the secondary pressure is taken out through ports 1, 2, 3 and 4 provided at the bottom face.



CROSS SECTION



The construction of the pilot value is shown in the attached cross section drawing. The casing has vertical holes in which reducing values are assembled.

The pressure reducing section is composed of the spool (3), spring (5) for setting secondary pressure, return spring (7), spring seat (6) and shim (4). The spring for setting the secondary pressure has been generally so preset that the secondary pressure is 7.6 to 28.5 kgf/cm². The spool is pushed against the push rod (9) by the return spring.

When the push rod is pushed down by tilting the handle, the spring seat comes down simultaneously and changes setting of the secondary pressure spring.

2. FUNCTIONS

1) FUNDAMENTAL FUNCTIONS

The pilot valve is a valve that controls the spool stroke, direction, etc of a main control valve. This function is carried out by providing the spring at one end of the main control valve spool and applying the output pressure (secondary pressure) of the pilot valve to the other end.

For this function to be carried out satisfactorily, the pilot valve is composed of the following elements.

- (1) Inlet port (P) where oil is supplied from hydraulic pump.
- (2) Output ports (1, 2, 3 & 4) to apply pressure supplied from inlet port to ends of control valve spools.
- (3) Tank port (T) necessary to control the above output pressure.
- (4) Spool to connect output port to inlet port or tank port.
- (5) Mechanical means to control output pressure, including springs that work on the above spools.

2) FUNCTIONS OF MAJOR SECTIONS

Item numbers are based on the type L1.

The functions of the spool (3) are to receive the supply oil pressure from the hydraulic pump at its port P, and to change over oil paths to determine whether the pressure oil of port P is led to output ports 1, 2, 3 & 4 or the output port pressure oil to tank port T.

The spring (5) works on this spool to determine the output pressure.

The change the deflection of this spring, the push rod (9) is inserted and can slide in the plug (8).

For the purpose of changing the displacement of the push rod through the swash plate (15) and adjusting nut (16) are provided the handle assy (20) that can be tilted in any direction around the fulcrum of the universal joint (14) center.

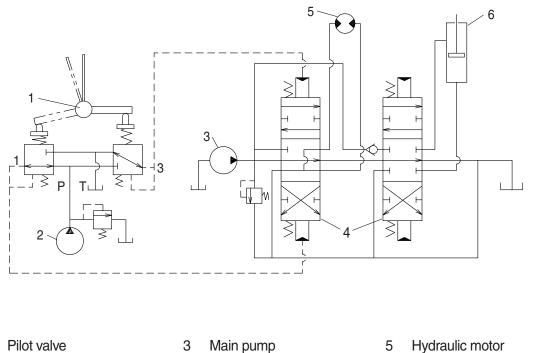
The spring (7) works on the case (1) and spring seat (6) and tries to return the push rod (9) to the zero-displacement position irrespective of the output pressure, securing its resetting to the center position.

This also has the effect of a reaction spring to give appropriate control feeling to the operator.

3) OPERATION

The operation of the pilot valve will be described on the basis of the hydraulic circuit diagram shown below and the attached operation explanation drawing.

The diagram shown below is the typical application example of the pilot valve.



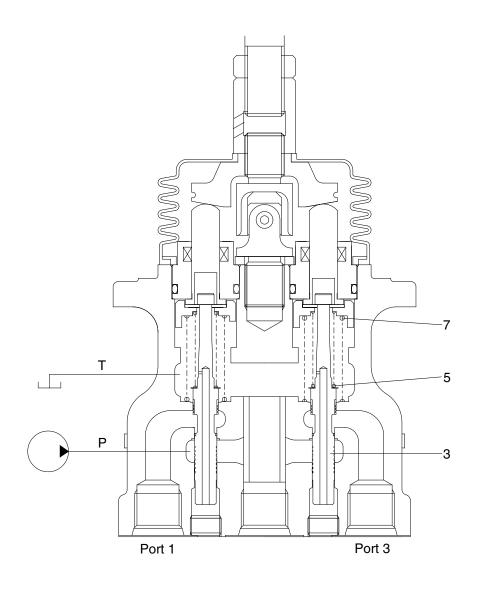
2 Pilot pump

1

- 4 Main control valve

2-70

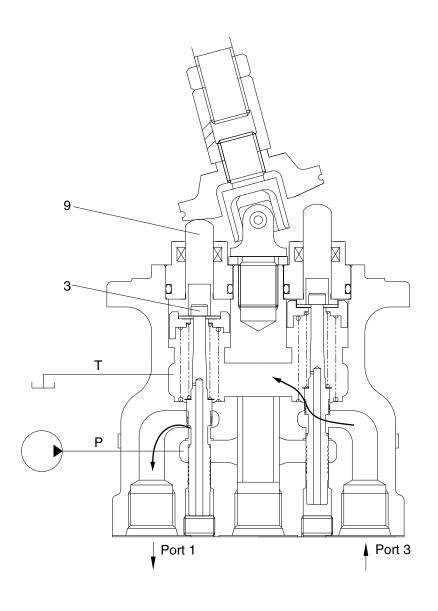
6 Hydraulic cylinder (1) Case where handle is in neutral position



300L2RL03

The force of the spring (5) that determines the output pressure of the pilot valve is not applied to the spool (3). Therefore, the spool is pushed up by the spring (7) to the position of port (1, 3) in the operation explanation drawing. Then, since the output port is connected to tank port T only, the output port pressure becomes equal to tank pressure.

(2) Case where handle is tilted



300L2RL04

When the push rod (9) is stroked, the spool (3) moves downwards.

Then port P is connected with port (1) and the oil supplied from the pilot pump flows through port (1) to generate the pressure.

When the pressure at port (1) increases to the value corresponding to the spring force set by tilting the handle, the hydraulic pressure force balances with the spring force. If the pressure at port (1) increases higher than the set pressure, port P is disconnected from port (1) and port T is connected with port (1). If it decreases lower than the set pressure, port P is connected with port (1) and port T is disconnected from port 1.

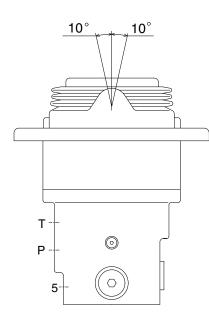
In this manner the secondary pressure is kept at the constant value.

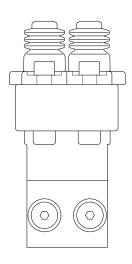
Besides, in some type, when the handle is tilted more than a certain angle, the upper end of the spool contacts with the inside bottom of the push rod and the output pressure is left to be connected with port P.

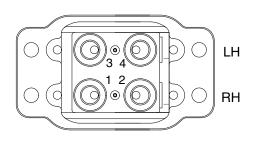
GROUP 6 RCV PEDAL

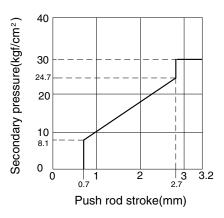
1. STRUCTURE

The casing has the oil inlet port P (primary pressure), and the oil outlet port T (tank). In addition the secondary pressure is taken out through ports 1, 2, 3 and 4 provided at the bottom face.

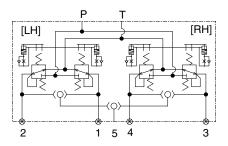












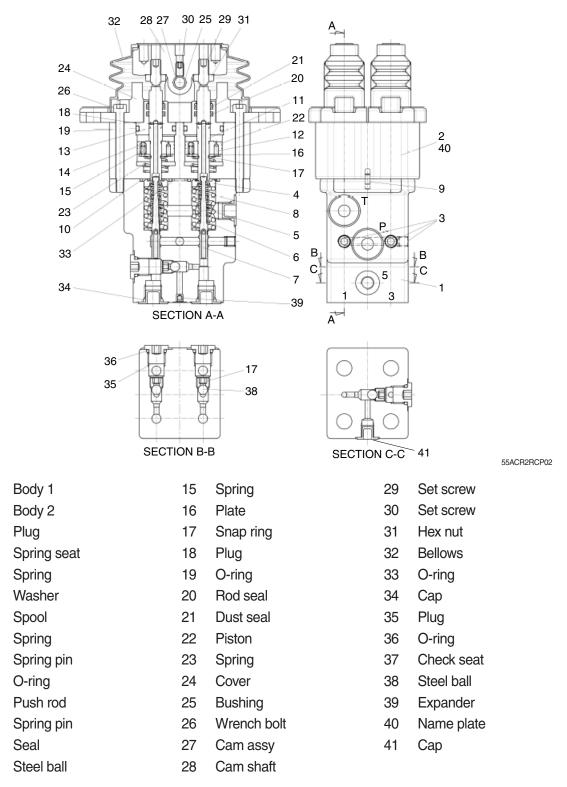
Port	Port name	Port size
Р	Pilot oil inlet port	PF 1/4
Т	Pilot oil return port	
1	Travel (LH, backward)	
2	Travel (LH, forward)	
3	Travel (RH, backward)	
4	Travel (RH, forward)	
5	Travel alarm	PT 1/8

CROSS SECTION

The construction of the RCV pedal is shown in the below drawing. The casing has vertical holes in which reducing valves are assembled.

The pressure reducing section is composed of the spool (7), spring (5) for setting secondary pressure, return spring (8), spring seat (4) and washer (6). The spring for setting the secondary pressure has been generally so preset that the secondary pressure is 8.1 to 24.5 kgf/cm² (depending on the type). The spool is pushed against the push rod (11) by the return spring.

When the push rod is pushed down by tilting pedal, the spring seat comes down simultaneously and changes setting of the secondary pressure spring.



2. FUNCTION

1) FUNDAMENTAL FUNCTIONS

The pilot valve is a valve controls the spool stroke, direction, etc of a main control valve. This function is carried out by providing the spring at one end of the main control valve spool and applying the output pressure (secondary pressure) of the pilot valve to the other end.

For this function to be carried out satisfactorily, the pilot valve is composed of the following elements.

- (1) Inlet port (P) where oil is supplied from hydraulic pump.
- (2) Output port (1, 2, 3 & 4) to apply pressure supplied from inlet port to ends of control valve spools.
- (3) Tank port (T) necessary to control the above output pressure.
- (4) Spool to connect output port to inlet port tank port.
- (5) Mechanical means to control output pressure, including springs that work on the above spools.

2) FUNCTIONS OF MAJOR SECTIONS

The functions of the spool (7) are to receive the supply oil pressure from the hydraulic pump at its port P, and to change over oil paths to determine whether the pressure oil of port P is led to output ports 1, 2, 3 & 4 or the output spool to determine the output pressure.

The spring (5) works on this spool to determine the output pressure.

The change the deflection of this spring, the push rod (11) is inserted and can slide in the plug (18). For the purpose of changing th displacement of the push rod through the cam (27) and steel ball (28) are provided the pedal that can be tilted in any direction around the fulcrum of the cam (27) center.

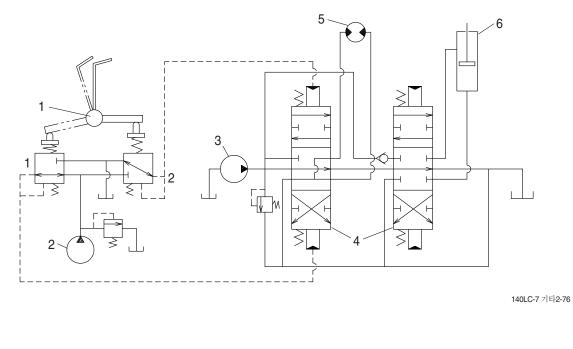
The spring (8) works on the casing (1) and washer (6) and tries to return the push rod (11) to the zero-displacement position irrespective of the output pressure, securing its resetting to the center position.

This also has the effect of a reaction spring to give appropriate control feeling to the operator.

3) OPERATION

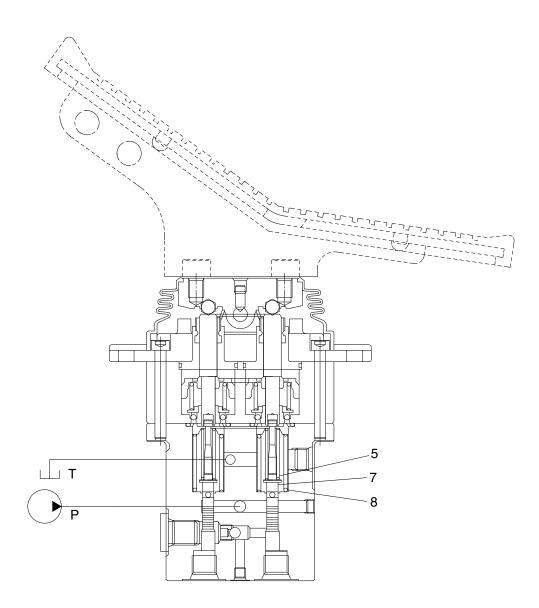
The operation of the pilot valve will be described on the basis of the hydraulic circuit diagram shown below ant the attached operation explanation drawing.

The diagram shown below is the typical application example of the pilot valve.



- 1 Pilot valve
- 2 Pilot pump
- 3 Main pump
- 4 Main control valve
- 5 Hydraulic motor
- 6 Hydraulic cylinder

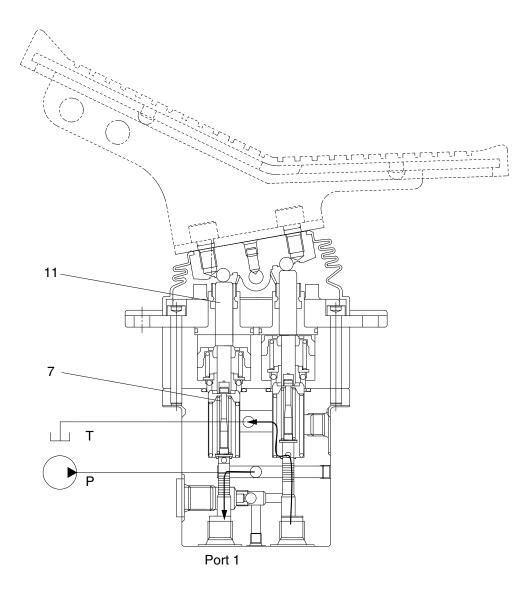
(1) Case where pedal is in neutral position



35AZ2RCP04

The force of the spring (5) that determines the output pressure of the pilot valve is not applied to the spool (7). Therefore, the spool is pushed up by the spring (8) to the position of port 2 in the operation explanation drawing. Then, since the output port is connected to tank port T only, the output port pressure becomes equal to tank pressure.

(2) Case where pedal is tilted



35AZ2RCP05

When the push rod (11) is stroked, the spool (7) moves downwards.

Then port P is connected with port 1, and the oil supplied from the pilot pump flows through port 1 to generate the pressure.

When the pressure at port 1 increases to the value corresponding to the spring force set by tilting the handle, the hydraulic pressure force balances with the spring force. If the pressure at port 1 increases higher than the set pressure, port P is disconnected from port 1 and port T is connected with port 1. If it decreases lower than the set pressure, port P is connected with port 1 and port T and port 1.

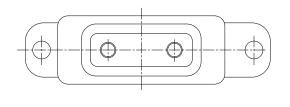
In this manner the secondary pressure is kept at the constant value.

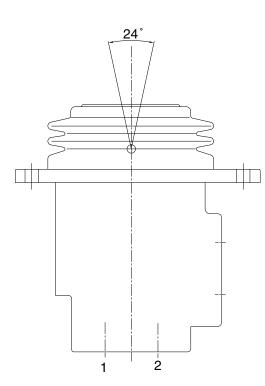
3. BOOM SWING PEDAL

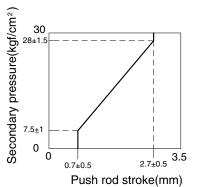
1) STRUCTURE

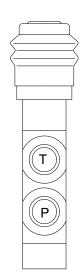
The casing has the oil inlet P (primary pressure) and the oil return port (tank).

In addition the secondary pressure is taken out through port 1 and port 2 provided at the housing bottom face.

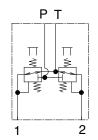








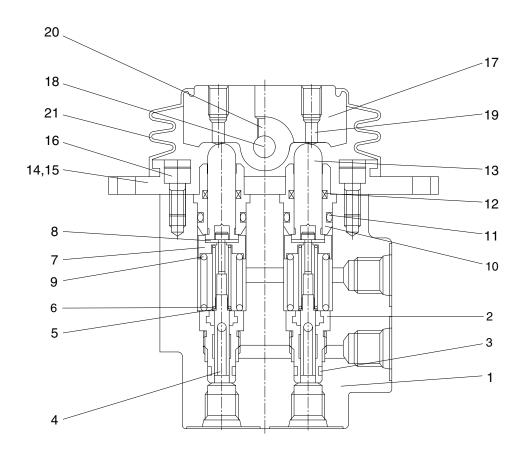
55ACR2BS01



Hydraulic circuit

Port	Port name	Port size
Р	Pilot oil inlet port	PF 1/4
Т	Pilot oil return port	
1	Boom swing (LH)	
2	Boom swing (RH)	

2) COMPONENT



- 1 Body
- 2 Plug
- 3 O-ring
- 4 Spool
- 5 Spring seat
- 6 Spring
- 7 Spring seat

- 8 Stopper
- 9 Spring
- 10 Plug
- 11 O-ring
- 12 Rod seal
- 13 Push rod
- 14 Cover

31MT-20050A

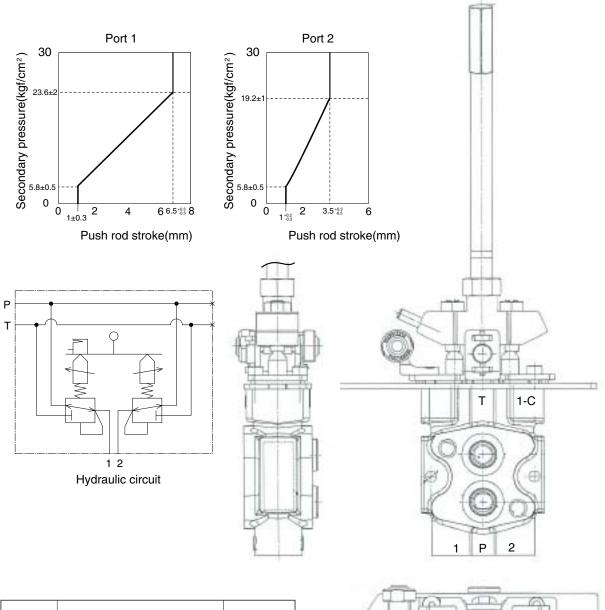
- 15 DU bush
- 16 Wrench bolt
- 17 Cam
- 18 Pin
- 19 Adjust screw
- 20 Socket bolt
- 21 Bellows

4. DOZER LEVER

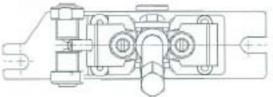
1) STRUCTURE

The casing has the oil inlet P (primary pressure) and the oil return port (tank).

In addition the secondary pressure is taken out through port 1 and port 2 provided at the housing bottom face.

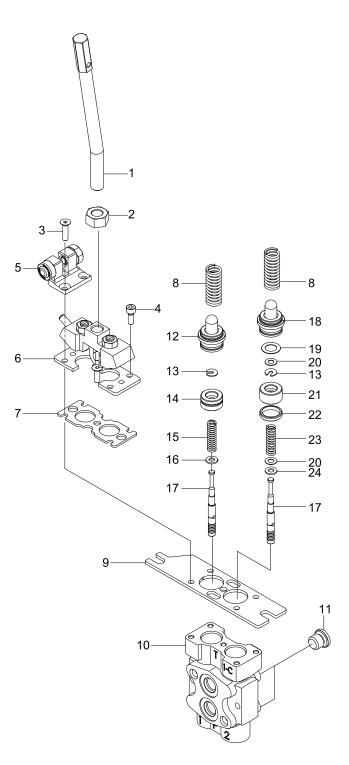


Port	Port	Port size
Р	Pilot oil inlet port	PF 1/4
Т	Pilot oil return port	PF 1/4
1	Dozer blade up port	PF 1/4
2	Dozer blade down port	PF 1/4



55ACR2DL01

2) COMPONENT



35AZ2DL02

- 1 RCV lever
- 2 Lever nut
- 3 Screw
- 4 Screw
- 5 Bracket
- 6 Upper body
- 7 Upper plate
- 8 Spring

- 9 Lower plate
- 10 Lower body
- 11 Plug
- 12 Plunger
- 13 Retainer
- 14 Bushing
- 15 Spring
- 16 Seal washer

- 17 Rod
- 18 Plunger
- 19 Spacer
 - 20 Spacer
 - 21 Bushing
 - 22 Spacer
 - 23 Spring
- 24 Gasket